Consumer Appliance, Widget, Gadget

A Better Mouse Trap

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APPLICATION OPERATION:

My application uses a PIC12C508 to produce realistic sounding mouse-like coos that all mice are sure to find seductive. The entire circuit should be imbedded in, or at least placed, near a baited mouse-trap for best effect.

The heart of the circuit is a pseudo-random number generator that determines both the time between squeaks, and the number of chirps in each squeak. In operation, the watchdog timer is used to wake the mouse up at a constant half-second rate. If the randomly determined, one to sixteen periods have passed, the mouse will emit a squeak. Squeaks consist of from one to four chirps, and each chirp is a tone that sweeps from about 5KHz to 10KHZ, in about 30mSec.

The circuit operates on two AAA dry cells, and drives a standard piezoelectric buzzer through a 4.7K resistor via a two pin push-pull output. No other components are required.

Block Diagram:

Operation is straight-forward, as described above.

Flow Chart:

Operation is straight-forward, as described above.

Graphical hardware representation:

This is probably described easier than I can draw it:

- The heart of the circuit is an 8-pin PIC12C508.
- Two AAA dry cells are connected in series to form a 3V supply, then connected with the positive lead to pin 1 of the PIC12C508, and the negative one to pin 8.
- Unused pins 2, 3, 4, and 5 are all connected to pin 1.
- Pin 7 has a 4.7K resistor connected to it with the other side of the resistor connected to either one of the wires on a piezoelectric buzzer. The other buzzer wire goes to pin 6.
- The value of the 4.7K resistor is not critical. It should be at least 1K to limit the current into the buzzer, and increased from there, to limit the volume to a pleasing level (depends on the efficiency of the buzzer).

APPENDIX A: SOURCE CODE

```
;
;                                          MouseTrap
;                                          =========
;                                                                    by Jim Nagy, Sept. 1997
;
;   A solid state mouse (the four legged kind) simulator, using the PIC12C508.
;
;   This circuit produces realistic-sounding mouse-like coos that all mice
;   are sure to find seductive. The circuit should be installed near
;   a baited mouse-trap for best effect.
;
;   This circuit is powered by a 3V source, and directly drives a
;   piezoelectric buzzer. Circuit connections are as follows:
;        A piezoelectric buzzer is connected through a series 4.7K

;          resistor to pins 6&7 (GP0&1)
;       +3V is connected to pin 1, gnd to pin 8
;       pins 2,3,4, and 5 should be tied to either pin 1 or 8
;
;    ***************************************************************************

; Program equates
TMin    EQU D'16'          ; Mouse chirps are frequency sweeps from about 5-10KHz
TMax    EQU D'32'          ; the freq. is approx 166000/T

; Standard Equates
W       EQU 0
F       EQU 1

GPWUF   EQU 7
PA0             EQU 5
TO              EQU 4
PD              EQU     3
Z               EQU     2
Zero    EQU 2
DC              EQU 1
C               EQU     0
Carry   EQU     0

MCLRDisabled   EQU 0
MCLREnabled    EQU H'10'
CodeProtect    EQU 0
NoCodeProtect  EQU H'08'
WDTDisabled    EQU 0
WDTEnabled       EQU H'04'
IntRCOsc         EQU H'02'
ExtRCOsc         EQU H'03'
XTOsc          EQU H'01'
LPOsc          EQU 0

; '508 Registers
INDF      EQU   H'00'
TMR0      EQU   H'01'
PCL             EQU     H'02'
STATUS    EQU   H'03'
FSR             EQU     H'04'
OSCCAL    EQU   H'05'
GPIO      EQU   H'06'

; program variables
LByte     EQU H'07'        ; random number variables
HByte     EQU H'08'        ; numbers are generated as 2bytes+carry
CBit      EQU H'09'
```

```
RNum     EQU H'07'        ; Generated random number...same as 'LByte'

WDTimes  EQU H'0A'        ; Mouse only chirps after 'WDTimes' wakeups
Count    EQU H'0A'        ; Dual use reg - only used during a chirp

ChirpCnt EQU H'0B'        ; # of chirps in the squeak
CycleCnt EQU H'0C'        ; counts cycles during a chirp
DelayCnt EQU H'0D'        ; delay counter for waveform generation


;   ******************************************
;   Setting the ID words...
        ORG H'0200'
ID0     Data.WH'0000'
ID1     Data.WH'0000'
ID2     Data.WH'0003'
ID3     Data.WH'0008'

;   ******************************************
;   and the Fuses...
        ORG H'0FFF'
CONFIG  Data.W  MCLRDisabled + NoCodeProtect + WDTEnabled + IntRCOsc


;   ******************************************
;   PIC starts here on power up...
;   ******************************************

        ORG H'00'

        MOVWFOSCCAL    ; store the factory osc. calibration value

;   subroutines must be in the low page, so jump to higher memory...
        BTFSCSTATUS,TO ; check if we're here from WDT timeout
        GOTOInit       ; no, do a full reset
        BTFSCSTATUS,PD ; was a timeout, but was it a wakeup call
        GOTOInit       ; no - it was a code error
        GOTOMain       ; yes, was a wakeup


;   ******************************************
;       Chirp
;   Each mouse squeak consists of a series of 1 to 4 chirps.
;   Each chirp lasts about 30mS, and consists of 12 cycles at each
;   frequency from a min set by TMax, to the maximum freq, set by TMin:

ChirpMOVLWTMax         ; get the initial waveform period
        MOVWF   Count      ; and save it
ch1     MOVLW   D'12'      ; 12 cycles at each frequency
        MOVWF   CycleCnt

ch2     MOVF    Count,W        ; load the count(delay) value
        BSF     GPIO,0     ; and produce one cycle
        CALL    DelayLoop
        BCF     GPIO,0
        MOVF    Count,W
        BSF     GPIO,1
        CALL    DelayLoop
        BCF     GPIO,1
        DECFSZ  CycleCnt,F ; keep repeating
        GOTO    ch2

        DECF    Count,F        ; reduce count to increase frequency
        MOVLW   TMin
        SUBWF   Count,W        ; compare to the min period value
        BTFSC   STATUS,Carry; C is clear if Count<TMin
```

```
        GOTO    ch1
        RETLW   0


;   ****************************************
;       DelayLoop
;   A simple delay routine...

DelayLoop
        MOVWF   DelayCnt        ; save the count value
d1      DECFSZ  DelayCnt,F      ; count down,
        GOTO    d1                      ; and loop,
        RETLW   0                       ; 'til we're done



;   ****************************************
;       Random
;   Generates a 'random' byte in RNum.
;   Maintains a 2 byte shift register (LByte and HByte) that has an input
;   provided by the XNOR of the inverse of the 13th bit and the carry out
;   bit. Generates one bit at a time, so calls itself 8 times to form a byte.

Random MOVF HByte,F             ; have to catch the special case where all
            BTFSS     STATUS,Zero  ; 16 bits are 0
            GOTO      r1
            MOVF      LByte,F
            BTFSS     STATUS,Zero
            GOTO      r1
            MOVF      TMR0,W        ; both bytes are zero, seed with the low byte
            MOVWF     LByte         ; with the timer contents
            BTFSS     STATUS,Zero   ; but even the timer might read zero
            GOTO      r1
            DECF      LByte,F           ; so then, just seed with FF

r1          CALL RLoop              ; 7 calls and a fall-through gives 8 calls...
            CALL RLoop
            CALL RLoop
            CALL RLoop
            CALL RLoop
            CALL RLoop
            CALL RLoop

RLoopMOVF   CBit,F                      ; the XNOR is based on the carry and 13th bits
            BTFSS   STATUS,Zero             ; check the 'carry bit'
            GOTO    CarryWas1

CarryWas0
            BTFSC   HByte,4                     ; C=0, so check bit 13
            INCF    CBit,F                  ; if it's 1, we'll rotate in a 1
            GOTO    SetCarry

CarryWas1
            CLRF    CBit                    ; assume the new carry will be 0
            BTFSS   HByte,4                     ; which it will be if bit13 is 1
            INCF    CBit,F                  ; else set CBit to 1 (b13=0)

SetCarry
            CLRW                            ; start with W=0
            ADDWF   CBit,F                  ; adding 0 to anything forces C=0
            BTFSS   STATUS,Zero             ; if CBit=0, go on
            SUBWF   CBit,F                  ; else, set C=1

RotateRLF   LByte,F                         ; rotate the new bit into the shift reg
            RLF     HByte,F
            CLRF    CBit                    ; then set CBit to the current value of C
```

```
                BTFSC   STATUS,Carry
                INCF    CBit,F
                RETLW   0


;       ****************************************
;               Wait
;       Provides a 50mS delay - careful it uses Count reg!

Wait    MOVLW   D'65'
                MOVWF   Count               ; loop counter
s1              MOVLW   H'FF'
                CALL    DelayLoop           ; delay 0.77mS
                DECFSZ  Count,F             ; and repeat
                GOTO    s1
                RETLW   0


;   ****************************************
;   Power On jumps to here...either Init, or Main
;   ****************************************

Init    CLRF    WDTimes                     ; force a single chirp this time
                CLRF    ChirpCnt
                INCF    ChirpCnt,F
Main    CLRF    GPIO                        ; Init the port - WDT always clears it
                MOVLW   B'00111100'             ; GP0 and GP1 are outputs, others are inputs
                TRIS    GPIO

                CLRWDT                          ; Set up the timers...
                MOVLW   B'11001101'         ; int clock to TMR0, WDT uses /32 (0.5s wakeup)
                OPTION                          ; no pullups, and no wakeup on change

                MOVF    WDTimes,F           ; check if WD has timed out enough times
                BTFSC   STATUS,Zero
                GOTO    Squeak              ; counted down to zero - ready for a squeak
                DECF    WDTimes,F           ; else count this time,
                SLEEP                           ; and wait

m1              CALL    Wait                ; A squeak is chirpcnt chirps
Squeak  CALL    Chirp               ; with pauses in between
                DECFSZ  ChirpCnt,F
                GOTO    m1

                CLRWDT                      ; been busy... make sure we won't be interrupted
                CALL    Random              ; let's get another random byte

                MOVF    RNum,W              ; and determine the next ChirpCount...
                ANDLW   B'00000011'         ; only use the last 2 bits for the count
                MOVWF   ChirpCnt            ; but we can't have zero squeaks,
                INCF    ChirpCnt,F          ; so add 1

                SWAPF   RNum,W              ; now calculate the wakeup delay...
                ANDLW   B'00001111'         ; only use the last 4 bits (0-8 sec delay)
                MOVWF   WDTimes
                SLEEP                       ; that's all folks
END
```

NOTES: