



Discrete Logic Replacement

Control Seven-Segment Displays

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APPLICATION OPERATION

This application shows a technique for connecting two 7-segment displays directly to the PIC12C50X. For example, a 99-second timer is implemented.

Timer Description

This is a two-digit counter, which is incremented each second. An active low Reset input is available, it is not de-bounced (because it is a Reset input). Holding the Reset input low maintains the counter in '00'.

Display Technique

Common anode displays are used in this circuit.

The display cathodes are driven with four I/O lines (GP0, GP1, GP2 and GP5). The GP4 line is used to select which display is driven, through two transistors connected to each display's anode.

Each digit is driven in two steps, some segments in the first step and the other segments in the second step, depending on the number displayed. With a 60 Hz refresh, two digits driven in two steps need to be updated 240 times per second (I chose 244), that is every 4.1 mS.

A useful feature of PICmicros is the possibility of changing an I/O line from output to input and vice-versa 'on the fly'. This allows for the implementation of input and output circuitry at the same time. In fact, I used this feature to get a third state (hi-Z) at selected I/O pins in selected moments. Combining this with the high sink/source current capability and using some diodes it is possible to select which segments are lit.

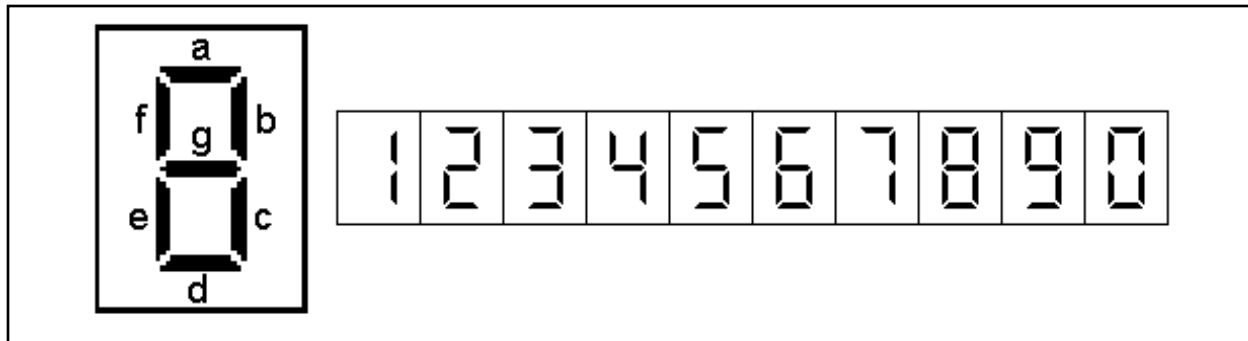
Each pin has two segments connected through two resistors (GP1 has only one). For example, GP5 is connected to segments **a** and **c** (Figure 1) through two resistors. A diode is also connected to each segment. A '0' in GP5 will turn on both **a** and **c**. If GP2 has a '1' at the same time as the **a** segment, it will not turn on, because it is connected through a diode to GP2. Therefore, to turn on the **a** segment, GP2 must be held at '0' level (which also turns on segment **d** and **e**) or in hi-Z (segments **d** and **e** off). It works similar with other segments.

Each display is driven in two steps. This is because it is not always possible to turn some segments on and another off at the same time (for example, you can't turn on the **a**, **f** and **g** segments without turning on the **c** segment). In those cases, the segment drive is split into two steps.

There are some additional considerations that simplify (and even make possible) this method, helping to select where the diodes should be placed:

- The segment **e** can turn on only when segment **d** is on.
- The segment **a** never is off when the segment **d** is on.

FIGURE 1: PIN PLACEMENT



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With that information from the previous page, the following table can be made: Pin states for numbers display

						STEP1		STEP2							
N	a	b	c	d	e	f	g	GP5	GP2	GP1	GP0	GP5	GP2	GP1	GP0
0	1	1	1	1	1	1	0	0	H	H	1	H	0	0	
1	1	1	0	1	0	H	H	H	0	H					
2	1	1	1	1	1	0	0	0	1	H	1	H	0		
3	1	1			1	1	1	0	1	0	0	0	0	1	1
4	1	1	1	1	0	1	0	0	1	H	H	0			
5	1	1	1	1	1	0	0	1	0	H	H	H	H		
6	1	1	1	1	1	1	0	0	H	0	H	H	H	H	
7	1	1	1	0	H	0	H	H	H	H	H				
8	1	1	1	1	1	1	1	0	0	0	0	H	H	H	H
9	1	1	1	1	1	0	0	H	0	0	H	0	1	H	

Display Selection

The GP4 pin is connected to a PNP and to an NPN transistors, so, '0' in this line activates the display #1 ('units') and a '1' activates the display #2 ('tens').

Currents

The current in each segment is limited to approximately 8 mA. That is about 16 mA per pin, leaving a good margin; the anode currents are handled by the transistors.

In fact, high efficiency displays should be used to get brighter digits; I used standard displays that still work fine at these current levels.

Reset input

GP4 is switched as an input to sense the Reset switch. During this very short time, the two transistors connected to it may be working in a nonsaturated mode. This is not a problem as the GP0-GP2 and GP5 are turned to hi-z, thereby, preventing the segments from being driven. Even if those pins were not turned to hi-z, the time is so short that the segments driven during this time are not visible.

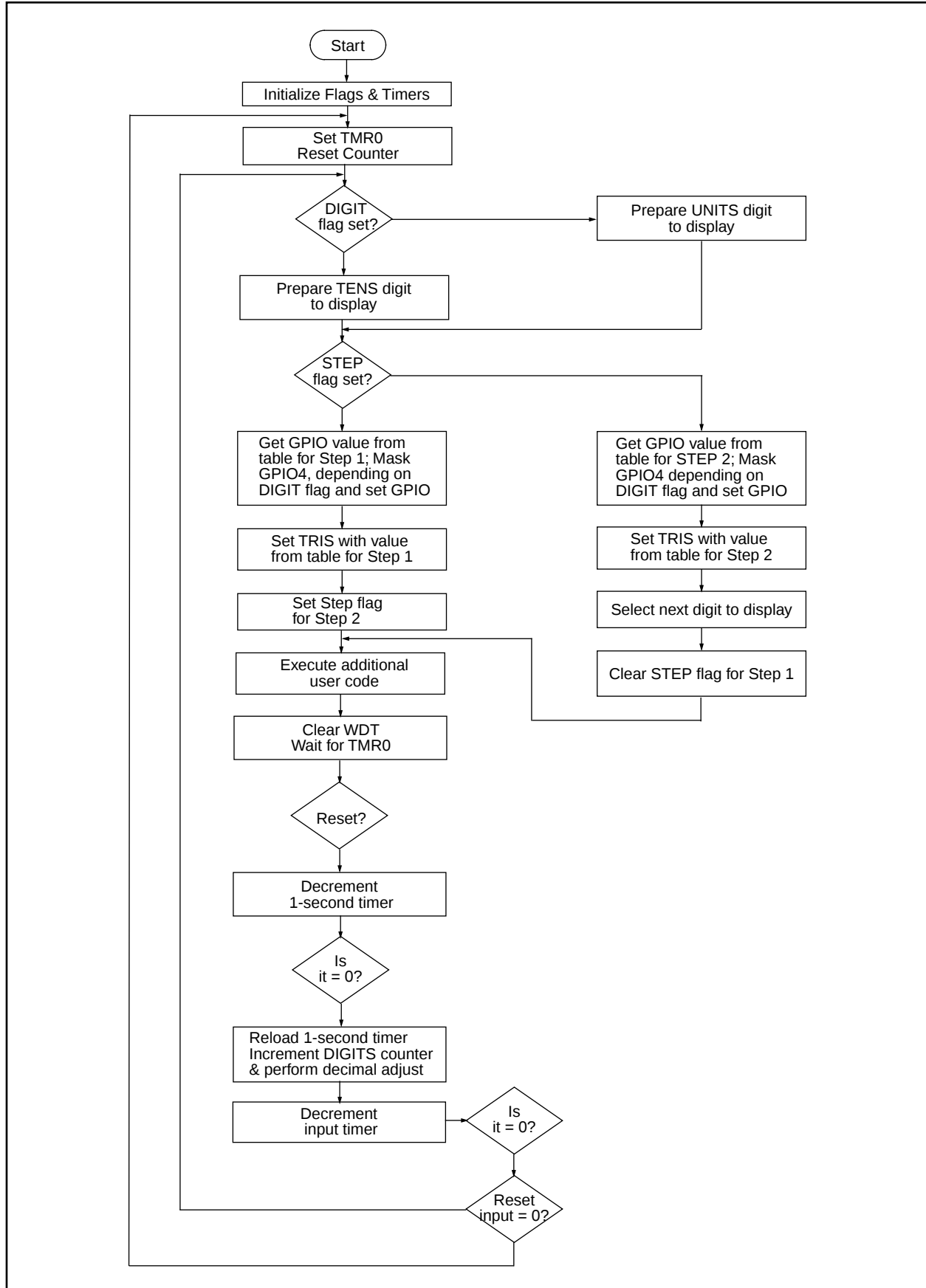
Using GP0-GP2 and GP5 as inputs is not possible without turning some segments on (affecting the number displayed).

GP3 is available to use.

Assembler/Compiler version

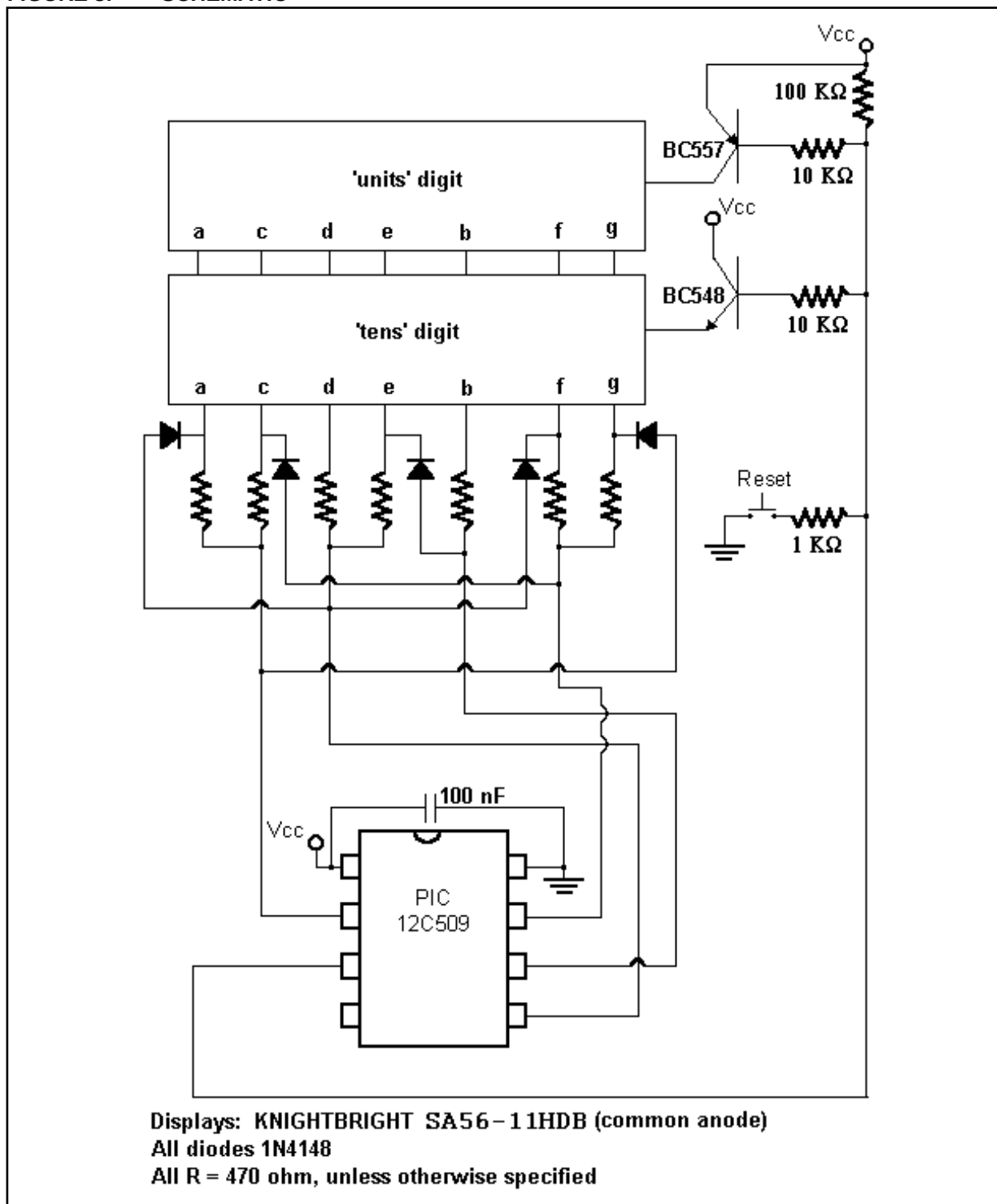
MPASM V0150, MPLAB V3.22.02

FIGURE 2: FLOW CHART



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FIGURE 3: SCHEMATIC



APPENDIX A: SOURCE CODE

```
LIST    P=12C509
        TITLE '7-SEGMENTS TIMER'
#include <p12C509.inc>
;*****
;   Program:          7SEGTMR.ASM
;
;   Revision date:
;
;               8-23-97
;*****
;
;__CONFIG b'000000001110'
;
;Timers:
;TMR0 is connected to the Prescaler which is set to 32. It is used
;for display timing. Each of the two digits is updated 62.5 times
;per second in two steps, that means, it completes 250 cycles per
;second. It is initialized to 125.
;There are two software timers based on TMR0. One is 'keytimer' allows
;the reset input to be read every 64 ms, it is initialized to 16.
;The other is 'tim' which is the timer used to measure 1 second. It is
;initialized to 250. It is decremented every TMR0 timeout, thus
;250 * 125 * 32 = 1000000; with a 4 Mhz clock it is a 1 second cycle.
;
; Timers constants
DISPLAYTIMER      equ    83h          ; Initialization value for TMR0
KEYCOUNT_BIT_VALUE equ    4          ; Init. for 'keytimer'. Bit 4 is set
; ==> count to 16 ==> Read input every 64 mS
SEC_TIMER         equ    0FAh        ; Init. value for 'tim'
;
; GPIO inputs pin assignment
RESET_IN          equ    4          ; GPIO4 ==> Reset counter
;
; flags1 bit assignment
STEP              equ    0          ; 0: STEP1 is displayed, 1: STEP2 is displayed
DIGIT             equ    7          ; 0: 'unites' digit, 1: 'tens' digit
;
; RAM assignation
;digit1 and digit2 MUST be in these locations (see step2)
digits            equ    07h        ; Memory location of two digit BCD counter
flags1            equ    08h        ; Flags
tim               equ    09h        ; 1 second timer
keytimer          equ    0Ah        ; Input timer
temp              equ    0Bh        ; Temporal use register
;
;Program
        org    03FFh
        MOVLW 020h
        org    0000h
start MOVWF OSCCAL          ; Set osc. compensation w/ original value
        CLRF flags1        ; Initialize flags
        CLRF keytimer
        BSF keytimer, KEYCOUNT_BIT_VALUE ; Initialize input timer

        MOVLW b'11010100'   ; Prescaler 1/32 for Timer0, no pull-ups
        OPTION

counter_reset
        CLRF digits        ; Clear counter
        MOVLW SEC_TIMER    ; Initialize 1 second timer
        MOVWF tim
        MOVLW DISPLAYTIMER ; Set timer
        MOVWF TMR0
        GOTO digitssel
;
; One second timer routine and increment counter
```

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```
;
main
    DECFSZ tim, F          ; Decrement 'one second' timer
    GOTO readinput

reload
    MOVLW SEC_TIMER        ; Reload 'one second' timer
    MOVWF tim

;
incda    MOVLW 07h          ; Routine for counter increment and
        ADDWF digits, F      ; decimal adjust
        BTFSC STATUS, DC
        GOTO test_c
        MOVLW 06h
        SUBWF digits, F
test_c    MOVLW 60h
        ADDWF digits, F
        BTFSS STATUS, C
        SUBWF digits, F
;
;Routine for RESET input reading
;
readinput
    DECFSZ keytimer, F      ; Decrement input counter
    GOTO digitssel
    BSF keytimer, KEYCOUNT_BIT_VALUE ; Reload input counter
    MOVLW b'00111111'      ; Set ALL pins as input
    TRIS GPIO
    NOP                    ; Discharge pins
;
; There is no need to debounce this input because it is a RESET input
;
res_test
    BTFSS GPIO, RESET_IN
    GOTO counter_reset      ; Input low ==> RESET
;
; Routine for display driving
;
digitssel
    MOVF digits, W
    BTFSC flags1, DIGIT      ; 'units' digit?, skip if yes
    SWAPF digits, W          ; 'tens' digit
    ANDLW b'00001111'        ; mask digit not displayed
    MOVWF temp               ; store digit to display in a temporal register

stepsel
    BTFSC flags1, STEP        ; Select step of digit to display
    GOTO step2

;
step1 CALL led_o1              ; Get output port STEP1 value
    BTFSS flags1, DIGIT      ; If displaying 'tens' skip
    ANDLW b'11101111'        ; Mask to select 'units' digit
    MOVWF GPIO                ; Output to port
    CALL led_iosel1          ; Get STEP1 i/o port direction selection
    TRIS GPIO                ; Set i/o port direction
    BSF flags1, STEP          ; Change flags to STEP2
    GOTO add_code

;
step2    CALL led_o2          ; Get output port STEP2 value
    BTFSS flags1, DIGIT      ; If displaying 'tens' skip
    ANDLW b'11101111'        ; Mask to select 'units' digit
    MOVWF GPIO                ; Output to port
    CALL led_iosel2          ; Get STEP2 i/o port direction selection
    TRIS GPIO                ; Set i/o port direction
    BCF flags1, STEP          ; Change flags to STEP1
;Select the next digit
    MOVLW b'10000000'        ; Complement bit 7 (DIGIT flag)
    ADDWF flags1, F           ; to select next digit to display
```

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```
;
;
add_code                                     ;
                                           ; Place additional code here
                                           ;
wait      CLRWDT                             ;
           MOVF TMR0, W                     ; Wait for timer
           BTFSS STATUS, Z
           GOTO wait
           MOVLW DISPLAYTIMER              ; Set timer
           MOVWF TMR0
           GOTO main
;
;
;
;STEP1: Table for ports output values selection
led_o1     MOVF temp, W
           ADDWF PCL, F
           RETLW b'00010000' ; #0
           RETLW b'00010100' ; #1
           RETLW b'00010001' ; #2
           RETLW b'00010100' ; #3
           RETLW b'00010100' ; #4
           RETLW b'00010010' ; #5
           RETLW b'00010000' ; #6
           RETLW b'00010000' ; #7
           RETLW b'00010000' ; #8
           RETLW b'00010000' ; #9
;
;
;STEP1: Table for ports I/O selection (Unused pins are set as inputs to
;get Hi-Z)
led_iosel1 MOVF temp, W
           ADDWF PCL, F ; Jump to decoding location
           RETLW b'00001011' ; #0
           RETLW b'00001001' ; #1
           RETLW b'00001000' ; #2
           RETLW b'00001000' ; #3
           RETLW b'00001000' ; #4
           RETLW b'00001000' ; #5
           RETLW b'00001010' ; #6
           RETLW b'00001101' ; #7
           RETLW b'00001000' ; #8
           RETLW b'00001000' ; #9
           RETLW b'00001100' ; #9
;
;
;STEP2: Table for ports output values selection
led_o2     MOVF temp, W
           ADDWF PCL, F
           RETLW b'00110000' ; #0
           RETLW b'00010000' ; #1
           RETLW b'00010100' ; #2
           RETLW b'00010011' ; #3
           RETLW b'00110000' ; #4
           RETLW b'00010000' ; #5
           RETLW b'00010000' ; #6
           RETLW b'00010000' ; #7
           RETLW b'00010000' ; #8
           RETLW b'00010010' ; #9
;
;
;STEP2: Table for ports I/O selection (Unused pins are set as inputs to
;get Hi-Z)
```

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```
led_iosel2      MOVF temp, W
                 ADDWF PCL, F      ; Jump to decoding location
                 RETLW b'00001100' ; #0
                 RETLW b'00101111' ; #1
                 RETLW b'00101010' ; #2
                 RETLW b'00001000' ; #3
                 RETLW b'00001110' ; #4
                 RETLW b'00101111' ; #5
                 RETLW b'00101111' ; #6
                 RETLW b'00101111' ; #7
                 RETLW b'00101111' ; #8
                 RETLW b'00101001' ; #9
;
END
```