



QUICKCODE™

Transmit One Byte Data with Synchronous Bit

*Author: Dag Bakken
Component-74 Eidsvold AS
RAHOLT
dag.bakken@microchip.com*

OVERVIEW

This piece of QuickCode is kind of a concept. The whole idea behind it, is to de-bounce without having to wait for the de-bouncing to finish without using interrupts or timers.

APPLICATION OPERATION:

The concept is extremely simple and easy to use, and generates very few words of code. The amount of code will vary greatly depending on how big your buffer must be. Usually, you can do with four bytes as in this piece of code. The two routines that handles the buffer/de-bouncing are totally 31 instructions with a four-byte deep buffer. A few instruction will be added if you require more buffer. The total amount of RAM is 4 for the buffer, 1 for 'last key' and 1 for return value (only 12-bit core of course). None of the functions needs any local variables.

The way this works, is by implementing some sort of multitasking. The basic idea behind it is that no tasks in your software should ever wait. By writing the entire software with this concept in mind, you can write software with virtually unlimited task-capacity. You can run fairly accurate PWMs together with other timers; All based on one timer. At the same time, you can implement the code supplied in this document to de-bounce some keys... and you can add software RS-232 'communication – simultaneously. Of course, as you add functions to the software, the clock-speed may need some adjustment.

One of the things I've used it for, is interfacing to displays in fairly time-critical applications. Displays do tend to be slow, and a PICmicro™ spend most of its time waiting when updating an entire display.

To make full use of this kind of programming, a message-based program-loop really helps the multitasking work. Both the message-based program-loop and the "no-wait" programming method uses very few instructions per loop, and this makes it easy to write large programs that uses very little time per pass.

SUPPLIED FUNCTIONS

- **char Debounce();**

This function will check the current key-buffer and last valid key-press. If test fails, a zero is returned; Meaning 'no key'.

- **void PutKey(char k)**

This function will push the currently pressed key (not de-bounced) into the key buffer.

- **char ReadKeyboard()**

This is the function that must handle the test for which key that is currently pressed, and make sure that it's pushed into the buffer. The return value should be the returned value from **char Debounce()**.

- **void main()**

In this example, this function handles the calling of **char ReadKeyboard()**. This may of course be handled by any function your software requires. Either way, the calling function must call the **char ReadKeyboard()** function at appropriate intervals for your application.

MICROCHIP TOOLS USED

MPLAB v3.22.02

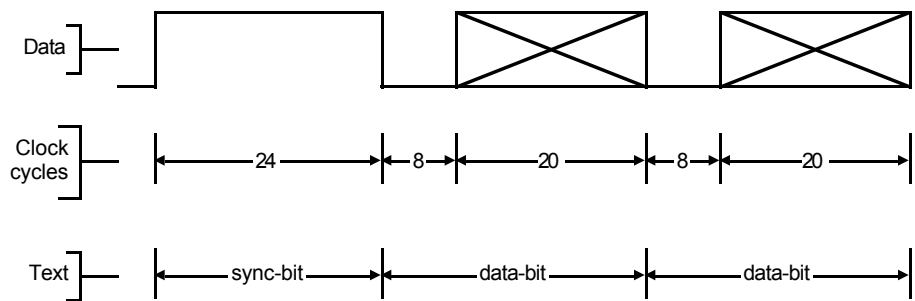
Assembler/Compiler version

CC5X v2.1H (C-Compiler). The generated ASM-code assembles with MPASMWIN v1.50. A straight cut n' paste from this document will work.

Microchip Technology Incorporated, has been granted a nonexclusive, worldwide license to reproduce, publish and distribute all submitted materials, in either original or edited form. The author has affirmed that this work is an original, unpublished work and that he/she owns all rights to such work. All property rights, such as patents, copyrights and trademarks remain with author.

Sensor Interface

Graphical Representation



This chart shows the data output (top-most line) as a function of clock-cycles (middle-line) with its respective sections denoted at the bottom.

APPENDIX A: S_μSOURCE CODE

A.1 CC5X v2.1H C-source

```
#include "c:\bruker\dag_s\progs\12c508.h"

#define BOOL bit

#pragma BOOL COL0 @ GPIO.0          // Assigned keyboard-column 0
#pragma BOOL COL1 @ GPIO.1          // Assigned keyboard-column 1
#pragma BOOL ROW0 @ GPIO.2          // Assigned keyboard-row 0
#pragma BOOL ROW1 @ GPIO.3          // Assigned keyboard-row 1

char retval;                        // This is used to simulate
                                   // return values on a 12-bit core.
char LastValidKey;                  // This is used to test for
                                   // changes in valid key-presses.
char KBuf1,KBuf2,KBuf3,KBuf4;      // Buffer for de-bouncing. Set
                                   // this buffer to whatever your
                                   // application requires.

/* This function will check the current contents of the buffer,
   and the last valid key-press. Returns the current valid
   key-press, or zero if it's not a valid key. */
char Debounce()
{
    retval=0;
    if (KBuf1!=KBuf2) return 0x00;    // Check buffer
    if (KBuf2!=KBuf3) return 0x00;    // Check buffer
    if (KBuf3!=KBuf4) return 0x00;    // Check buffer
    if (LastValidKey==KBuf1) return 0x00; // Check last de-bounced
                                         // value against current
                                         // de-bounced value.

    LastValidKey=KBuf1;                // Set this key-press
                                         // as valid.
    retval=KBuf1;                      // Return de-bounced
    return 0;                          // key-press
}

/* This function will put the current key-press in the de-bounce
   buffer */
void PutKey(char k)
{
    KBuf1=KBuf2;                      // PUSH value
    KBuf2=KBuf3;                      // PUSH value
    KBuf3=KBuf4;                      // PUSH value
    KBuf4=k;                          // PUSH value
}

/* This is the main function that checks the keyboard and handles
   all events. This function is provided as a guide-line on how
   to use the other de-bouncing features. */
char ReadKeyboard()
{
    COL0=1; COL1=0;
    if (ROW0)
    { PutKey('1');                    // Key '1' detected
      goto _FOUND_ONE;
    }
    if (ROW1)
    { PutKey('2');                    // Key '2' detected
      goto _FOUND_ONE;
    }
    COL0=0; COL1=1;
}
```

Sensor Interface

```
if (ROW0)
{ PutKey('3'); // Key '3' detected
  goto _FOUND_ONE;
}
if (ROW1)
{ PutKey('4'); // Key '4' detected
  goto _FOUND_ONE;
}
COL1=0;
PutKey(0x00); // If no key were pressed

_FOUND_ONE:
COL0=0; COL1=0;

Debounce(); // De-bounce, and return
return 0; // de-bounced value.
}

/* The main() function is provided so the program will compile if
you do a cut n' paste from this source into your editor. */
void main()
{
  do {
    ReadKeyboard(); // By executing this line at
    switch(retval) // certain intervals, keyboard
                  // will be de-bounced.

    {
      case '1': break; // Test
      case '2': break; // Test
      case '3': break; // Test
      case '4': break; // Test
    }
    /* Do something else while
       waiting for valid key-press */
  } while(1);
}
```

A.2 MPASM-code generated by CC5X v2.1H

```
; CC5X Version 2.1H, Copyright (c) B. Knudsen Data
; C compiler for the PIC16CXX microcontroller family
; ***** 1. Aug 1997 14:38 *****

        processor 12C508

Zero_    EQU    2
COL0     EQU    0
COL1     EQU    1
ROW0     EQU    2
ROW1     EQU    3
retval   EQU    0x08
LastValidKey EQU 0x09
KBuf1    EQU    0x0A
KBuf2    EQU    0x0B
KBuf3    EQU    0x0C
KBuf4    EQU    0x0D
k        EQU    0x07

        GOTO main

; FILE C:\TEMP\temp.c
        #include "c:\bruker\dag_s\progs\12c508.h"
        ;
        #define BOOL bit
        ;
        #pragma BOOL COL0 @ GPIO.0           // Assigned keyboard-column 0
        #pragma BOOL COL1 @ GPIO.1           // Assigned keyboard-column 1
        #pragma BOOL ROW0 @ GPIO.2           // Assigned keyboard-row 0
        #pragma BOOL ROW1 @ GPIO.3           // Assigned keyboard-row 1
        ;
        ;
        ;char retval;                        // This is used to simulate
        ;                                  // return values on a 12-bit core.
        ;char LastValidKey;                  // This is used to test for
        ;                                  // changes in valid key-presses.
        ;char KBuf1,KBuf2,KBuf3,KBuf4;       // Buffer for de-bouncing. Set
        ;                                  // this buffer to whatever your
        ;                                  // application requires.
        ;
        /* This function will check the current contents of the buffer,
        ;   and the last valid key-press. Returns the current valid
        ;   key-press, or zero if it's not a valid key. */
        ;char Debounce()
        ;{
Debounce
        ;   retval=0;
        CLRF  retval
        ;   if (KBuf1!=KBuf2) return 0x00;    // Check buffer
        MOVF  KBuf1,W
        XORWF KBuf2,W
        BTFSS 0x03,Zero_
        RETLW .0
        ;   if (KBuf2!=KBuf3) return 0x00;    // Check buffer
        MOVF  KBuf2,W
        XORWF KBuf3,W
        BTFSS 0x03,Zero_
        RETLW .0
        ;   if (KBuf3!=KBuf4) return 0x00;    // Check buffer
        MOVF  KBuf3,W
        XORWF KBuf4,W
        BTFSS 0x03,Zero_
        RETLW .0
```

Sensor Interface

```

; if (LastValidKey==KBuf1) return 0x00;// Check last de-bounced
MOVWF LastValidKey,W
XORWF KBuf1,W
BTFSC 0x03,Zero_
RETLW .0

;
; // value against current
; // de-bounced value.
; LastValidKey=KBuf1; // Set this key-press
MOVWF KBuf1,W
MOVWF LastValidKey
;
; // as valid.
; retval=KBuf1; // Return de-bounced
MOVWF retval
; return 0; // key-press
RETLW .0

;}
;
; /* This function will put the current key-press in the de-bounce
; buffer */
;void PutKey(char k)
;{
PutKey
MOVWF k
; KBuf1=KBuf2; // PUSH value
MOVWF KBuf2,W
MOVWF KBuf1
; KBuf2=KBuf3; // PUSH value
MOVWF KBuf3,W
MOVWF KBuf2
; KBuf3=KBuf4; // PUSH value
MOVWF KBuf4,W
MOVWF KBuf3
; KBuf4=k; // PUSH value
MOVWF k,W
MOVWF KBuf4
;}
RETLW .0
;
; /* This is the main function that checks the keyboard and handles
; all events. This function is provided as a guide-line on how
; to use the other de-bouncing features. */
;char ReadKeyboard()
;{
ReadKeyboard
; COL0=1; COL1=0;
BSF 0x06,COL0
BCF 0x06,COL1
; if (ROW0)
BTFSS 0x06,ROW0
GOTO m001
; { PutKey('1'); // Key '1' detected
MOVLW .49
CALL PutKey
; goto _FOUND_ONE;
GOTO m005
; }
; if (ROW1)
m001 BTFSS 0x06,ROW1
GOTO m002
; { PutKey('2'); // Key '2' detected
MOVLW .50
CALL PutKey
; goto _FOUND_ONE;
GOTO m005
; }
; COL0=0; COL1=1;

```

```
m002    BCF    0x06,COL0
        BSF    0x06,COL1
        ; if (ROW0)
        BTFSS 0x06,ROW0
        GOTO  m003
        ; { PutKey('3');
        ;                                     // Key '3' detected
        MOVLW .51
        CALL  PutKey
        ; goto _FOUND_ONE;
        GOTO  m005
        ; }
        ; if (ROW1)
m003    BTFSS 0x06,ROW1
        GOTO  m004
        ; { PutKey('4');
        ;                                     // Key '4' detected
        MOVLW .52
        CALL  PutKey
        ; goto _FOUND_ONE;
        GOTO  m005
        ; }
        ; COL1=0;
m004    BCF    0x06,COL1
        ; PutKey(0x00);
        ;                                     // If no key were pressed
        MOVLW .0
        CALL  PutKey
        ;
        ; _FOUND_ONE:
        ; COL0=0; COL1=0;
m005    BCF    0x06,COL0
        BCF    0x06,COL1
        ;
        ; Debounce();
        ;                                     // De-bounce, and return
        CALL  Debounce
        ; return 0;
        ;                                     // de-bounced value.
        RETLW .0
        ;}
        ;
        ;/* The main() function is provided so the program will compile if
        ; you do a cut n' paste from this source into your editor. */
        ;void main()
        ;{
main
        ; do {
        ; ReadKeyboard();
        ;                                     // By executing this line at
m006    CALL  ReadKeyboard
        ; switch(retval)
        ;                                     // By executing this line at
        MOVF  retval,W
        XORLW .49
        BTFSC 0x03,Zero_
        GOTO  m006
        XORLW .3
        BTFSC 0x03,Zero_
        GOTO  m006
        XORLW .1
        BTFSC 0x03,Zero_
        GOTO  m006
        XORLW .7
        BTFSC 0x03,Zero_
        GOTO  m006
        GOTO  m006
        ;
        ;                                     // certain intervals, keyboard
        ;                                     // will be de-bounced.
        ; {
        ; case '1': break;
        ;                                     // Test
        ; case '2': break;
        ;                                     // Test
        ; case '3': break;
        ;                                     // Test
```

Sensor Interface

```
        ;      case '4': break;          // Test
        ;      }
        ;      /* Do something else while
        ;      waiting for valid key-press */
        ;  } while(1);
        ;}
```

END

NOTES:

