

## Auto-calibration of the PIC12F6XX Internal RC Oscillator to $\pm 1\%$

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### INTRODUCTION

This application note describes a technique used to calibrate the internal oscillator on the PIC12F6XX devices. This technique allows the internal oscillator to be calibrated within  $\pm 1\%$ . See the test circuit shown in Figure 1.

This application note is useful in the following applications:

1. High volume production environment.
2. Battery applications using on-board calibration to recalibrate the internal RC oscillator as the battery voltage drops.
3. Applications that are exposed to a varying voltage and temperature range could have intelligent on-board recalibration.

### THEORY OF OPERATION

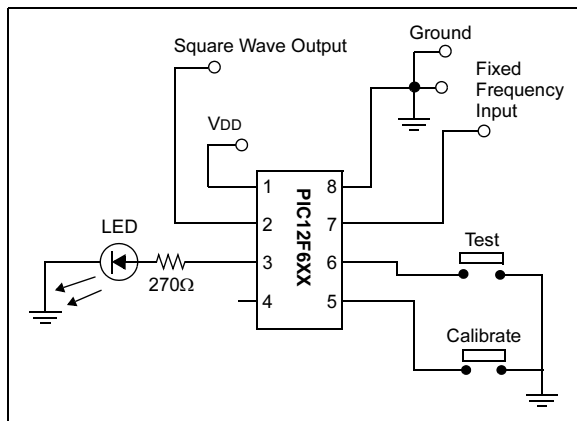
#### Equipment Used

- HP54645D Oscilloscope with digital probes
- AGILENT 33120A Function Generator
- HPE3620A Power Supply
- Digital multimeter with frequency counter

#### Definitions

- **Tolerance** - A firmware specified value indicating the allowed deviation in the measured period of a 5 kHz square wave output from a fixed frequency source.
- **Calibration Counter** - A firmware specified value indicating how many times to perform a calibration.

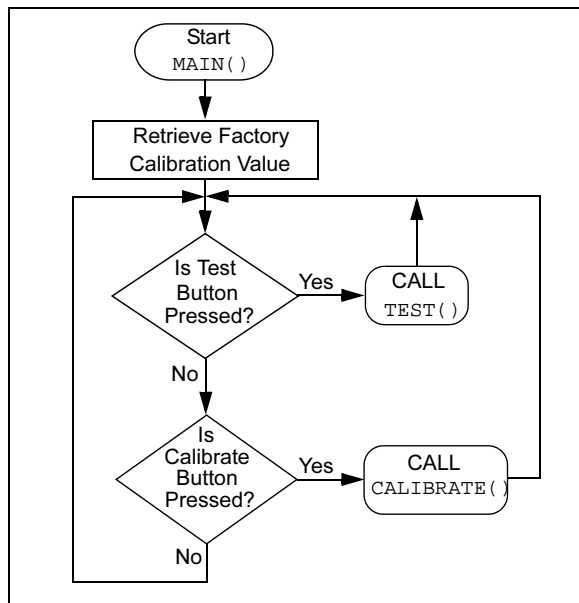
**FIGURE 1: TEST CIRCUIT**



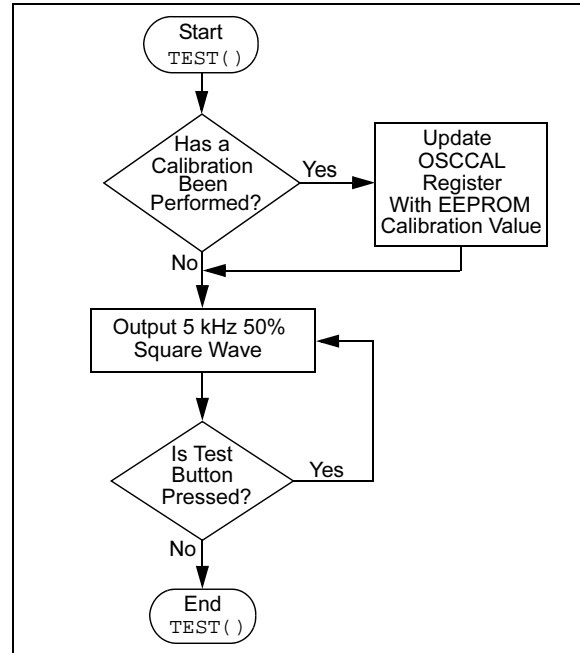
## Testing

To test the PIC12F6XX device, the firmware first determines if a calibration was performed. If a calibration was performed, the firmware loads the new value from EEPROM into the OSCCAL register. Otherwise, the original factory value is loaded into the OSCCAL register. If the device is calibrated, a 5 kHz square wave is generated by the PIC12F6XX and output on an I/O pin. By hooking up an oscilloscope or frequency counter to this pin, one can determine how precise the internal oscillator is calibrated by measuring the deviation of the frequency, or period of the square wave being output when compared to 5 kHz. See Figure 2 and Figure 3.

**FIGURE 2: MAIN ROUTINE**



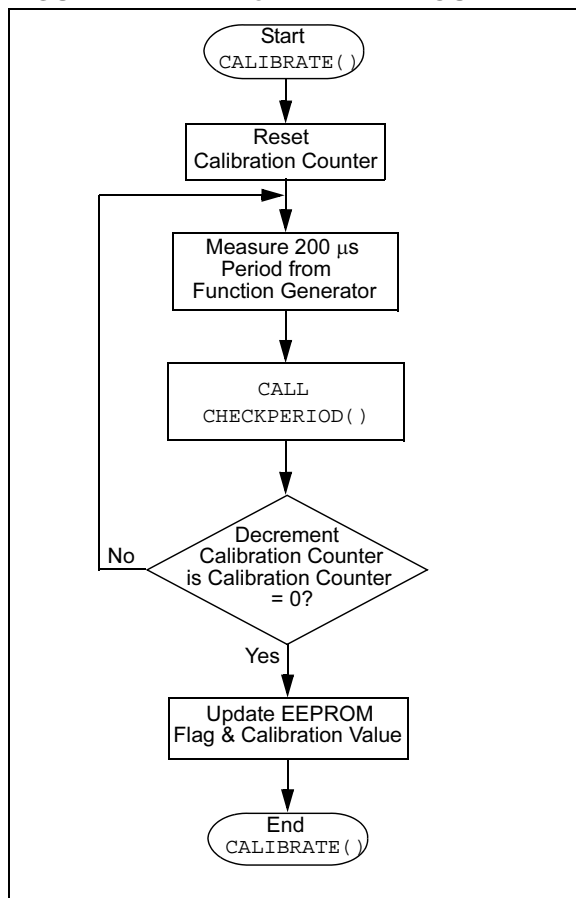
**FIGURE 3: TEST ROUTINE**



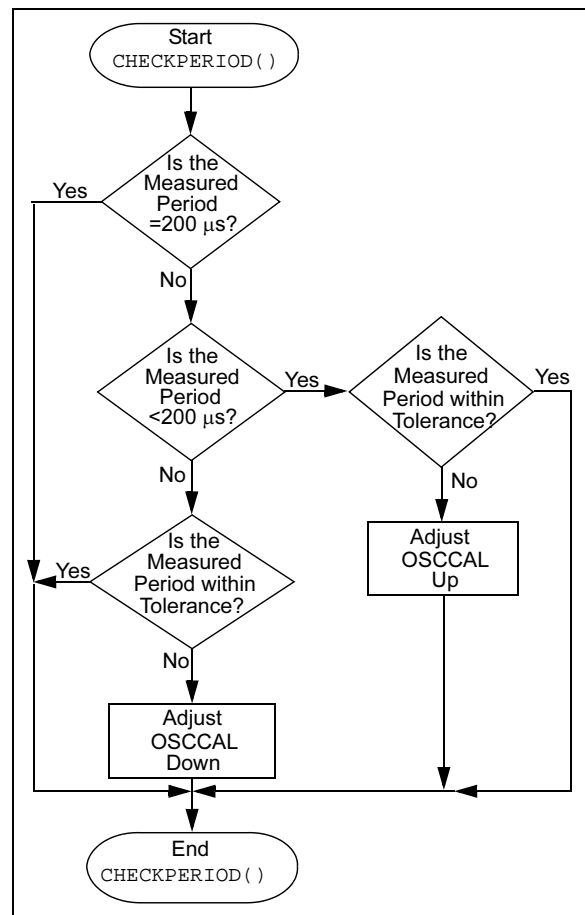
## Calibration

To calibrate the PIC12F6XX device, a 5 kHz 50% duty cycle square wave is injected into an I/O pin on the PIC12F6XX device. The firmware measures the period of the 5 kHz square wave and checks to see if it is within a specified tolerance. If the firmware determines that the PIC12F6XX internal oscillator is running faster than the specified tolerance, then it will decrement the value in the OSCCAL register by 1. If the firmware determines that the PIC12F6XX internal oscillator is running slower than the specified tolerance, then it will increment the value in the OSCCAL register by 1. The PIC12F6XX firmware will repeat the above procedure until the calibration counter reaches 0. After the firmware is finished calibrating the internal oscillator, the new calibration value is stored in EEPROM. See Figure 4 and Figure 5.

**FIGURE 4: CALIBRATE ROUTINE**



**FIGURE 5: CHECKPERIOD() ROUTINE**



## CONCLUSION

This application note shows a method for auto-calibration of the PIC12F6XX internal RC oscillator. In particular, using a fixed frequency source allowed calibration of the PIC12F6XX internal RC oscillator to be within  $\pm 1\%$ .

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**APPENDIX A: PIC12F6XX AUTO-CALIBRATION & TEST PROGRAM**

```

;*****
;PIC12F6XX Autocalibration & Test Program
;
;Version: 1.0
;Date: 10/21/02
;Author: Mike Rylee
;Description: This program calibrates the internal RC oscillator on the PIC12F6XX to the tolerance
;             specified in the #define TOLERANCE measurement parameter below. The oscillator is
;             calibrated using a 5kHz 50% square wave signal input on GP0 from a function generator.
;             The calibration is started by pushing the pushbutton connected to GP2.
;             After calibration a 5kHz test signal can be output on GP5 by the pushbutton connected
;             to GP1 to check the calibration.
;*****

list      p=12f675
#include <p12f675.inc>

__CONFIG _CP_OFF & _CPD_OFF & _BODEN_OFF & _MCLRE_OFF & _WDT_OFF & _PWRTE_ON &
INTRC_OSC_NOCLKOUT

;GENERAL PURPOSE REGISTERS
COUNTER EQU 0X20

;MEASUREMENT PARAMETERS
#define REFERENCEPERIOD .200 ;Reference Period In Microseconds
#define TOLERANCE .1 ;Tolerance Can Be Tweaked For Oscillator Accuracy
#define CALIBRATIONTIME .10 ;Number Of Times To Measure Signal During Calibration

;MAIN I/O
#define INPUT0 GPIO,0 ;Input Reference Waveform Of 5KHz
#define INPUT1 GPIO,1 ;Test Button
#define INPUT2 GPIO,2 ;Calibrate Button
#define OUTPUT GPIO,5 ;Outputs 5KHz Calibrated Waveform

;EEPROM Definitions
#define CALFLAGADR 0x7E ;Value of 0xA5 => Calibration Has Not Been Performed
                        ;Value of 0x5A => Calibration Has Been Performed
#define CALVALADR 0X7F ;Calibration Value

;DEBUG
#define LED GPIO,4 ;Debug LED

;*****
;Reset Vector
;*****
ORG 0x000
call 0x3FF ; Retrieve Factory Calibration Value
BANKSEL OSCCAL ; BANK1
movwf OSCCAL ; Load OSCCAL

```

```

        goto                INIT

;*****
;Initialization
;*****
INIT
        movlw              b'00001111' ;GP0-Input, GP1-Input, GP2-Input, GP4-Output,GP5-Output
        movwf              TRISIO
        clrf               ANSEL
        clrf               VRCON        ;Turn Off VREF
        BANKSEL            GPIO        ;BANK 0

        movlw              .7          ;Turn Off comparator
        movwf              CMCON

        BANKSEL            OPTION_REG ;BANK 1
        movlw              b'01001000' ;Pull Ups Enabled, Rising Edge, Assigned to WDT,
                                        ;Prescaler is 1:1 WDT

        movwf              OPTION_REG
        bsf                WPU,2       ;GP2 - Pullup Enabled
        bsf                WPU,1       ;GP1 - Pullup Enabled
        BANKSEL            GPIO        ;BANK0
        clrf               GPIO

;*****
;Main Program - This routine watches button INPUT1 & INPUT2
;                - Calls CALIBRATE() or Calls TEST()
;*****
MAIN
        btfss              INPUT1      ;Check Test Button
        goto               ONE
        btfsc              INPUT2      ;Check Calibration Button
        goto               MAIN

TWO
        bsf                LED
        call               CALIBRATE
        bcf                LED
        goto               MAIN

ONE
        bsf                LED
        call               TEST
        bcf                LED
        goto               MAIN

;*****
;Subroutines
;*****
;TEST() - This routine is used to test the OSCCAL value in the PIC12F6XX
;        - Checks If Calibration Was Performed
;        - Updates OSCCAL Value If Calibration Was Performed
;        - Outputs A 5 kHz 50% Square Wave On OUTPUT Until Pushbutton Is Released
;*****
TEST
        movlw              CALFLAGADR
        call               EEREAD
        sublw              0x5A
        btfss              STATUS,Z    ;Was Calibration Flag Set?
        goto               STARTTEST   ;No Don't Change Oscscal

        movlw              CALVALADR
        call               EEREAD      ;Yes Change The Oscscal
        BANKSEL            OSCCAL     ;BANK1

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```
        movwf      OSCCAL
        BANKSEL   GPIO          ;BANK0

STARTTEST                                ;The instructions below make a 5kHz 50% Square Wave
                                           ;Output On GP1 if the device is calibrated

        bsf       OUTPUT        ;1 us
        movlw     .31           ;Delay 99 us
        call      DELAYUS       ;99+1 = 100 us
        bcf       OUTPUT        ;1us
        movlw     .30           ;Delay 96 us
        call      DELAYUS
        btfs     INPUT1         ;1 us
        goto      STARTTEST     ;2 us =>1+96+1+2 = 100 us
        return

;*****
;Calibrate()- Measures A Period From The Input(GP0) Reference Signal
;           - Updates Oscscal Value
;           - Updates E^2
;*****
CALIBRATE
        movlw     CALIBRATIONTIME
        movwf     COUNTER       ;Calibration Counter

LOW0
        btfs     INPUT0         ;Wait To Sample Low Edge #0 (Makes Sure We Are
                                           ;Synchronized First Time Through)
        goto     LOW0

HIGH1
        btfs     INPUT0         ;Wait To Sample High Edge #1
        goto     HIGH1
        clrf     TMR0           ;Start Timer (Timer Will Be Behind By 5us After This
                                           ;Instruction)

LOW1
        btfs     INPUT0         ;Wait To Sample Low Edge #1
        goto     LOW1

HIGH2
        btfs     INPUT0         ;Wait To Sample High Edge #2
        goto     HIGH2
        movf     TMR0,W         ;Stop Timer (Timer Will Be Stopped 3us Late)
        addlw   .2             ;Timer Is Behind By 2us Total From Start To Stop
        call    CHECKPERIOD    ;See If Oscscal Needs To Be Adjusted

LOW2
        btfs     INPUT0         ;Wait To Sample Low Edge #2
        goto     LOW2
        decfsz   COUNTER,F      ;Decrement The Calibration Counter
        goto     HIGH1
        call    UPDATE_EE      ;Update E^2
        return

;*****
;Update_EE - This routine Updates Calibration Flag & Calibration Value
;*****
UPDATE_EE
        BANKSEL   EEDATA       ;BANK1
        movlw     0x5A         ;Update Calibration Flag
        movwf     EEDATA
        movlw     CALFLAGADR
        call      EEWRITE
        movf     OSCCAL,W
```

```

movwf      EEDATA
movlw     CALVALADR
call      EEWRITE      ;Update Calibration Value
BANKSEL   GPIO         ;BANK0
return

;*****
;CheckPeriod(W)- This routine computes the difference between the REFERENCEPERIOD and
;
;      MEASUREDPERIOD
;
;      - The MEASUREDPERIOD is contained in W when this routine is called
;
;      - The OSCCAL Is Adjusted Up or Down If The Period Is Outside The Specified
;
;      Tolerance
;*****
CHECKPERIOD
    sublw      REFERENCEPERIOD
    btfsc     STATUS,Z      ;If (ReferencePeriod - MeasuredPeriod = 0) Don't Change
                                ;OSCCAL
    return

    btfsc     STATUS,C      ;If (ReferencePeriod - MeasuredPeriod > 0) Oscillator
                                ;Could Be Too Fast
    goto      RUNNINGSLOW  ;Else Oscillator Could Be Too Slow

RUNNINGFAST
    xorlw     0xFF          ;Two's Complement Value
    addlw     .1
    sublw     TOLERANCE     ;If (Tolerance - (ReferencePeriod - MeasuredPeriod) = 0
                                ;Don't Change Oscal
    btfsc     STATUS,Z
    return
    goto      ADJUSTDOWN   ;Else Adjust Oscal Down

RUNNINGSLOW
    sublw     TOLERANCE     ;If (Tolerance - (ReferencePeriod - MeasuredPeriod) = 0
                                ;Don't Change Oscal
    btfsc     STATUS,Z
    return
    goto      ADJUSTUP     ;Else Adjust Oscal Up

ADJUSTDOWN
    BANKSEL   OSCCAL        ;BANK1
    movlw     .4
    subwf    OSCCAL,F      ;Adjust Oscal Down
    BANKSEL   GPIO         ;BANK0
    return

ADJUSTUP
    BANKSEL   OSCCAL        ;BANK1
    movlw     .4
    addwf    OSCCAL,F      ;Adjust Oscal Up
    BANKSEL   GPIO         ;BANK0
    return
;*****
;EEREAD(W) - Address To Read Is Contained In W When This Function Is Called
;*****
EEREAD
    BANKSEL   EEADR         ;BANK1
    movwf    EEADR
    bsf      EECON1,RD
    movf     EEDATA,W
    BANKSEL   GPIO         ;BANK0
    return

;*****
;EEWRITE(W) - Address To Read Is Contained In W When This Function Is Called

```

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```
;          - EEDATA Is Loaded Prior To This Function Call
;          - BANK1 must be selected before this function is called
;*****
EEWRITE
    movwf    EEADR
    bsf      EECON1,WREN
    bcf      INTCON, GIE
    movlw   0x55
    movwf   EECON2
    movlw   0xAA
    movwf   EECON2
    bsf      EECON1,WR

EECOMPLETE
    btfsc   EECON1,WR
    goto    EECOMPLETE
    bcf      EECON1,WREN
    return

;*****
;*****
;DELAYUS(W) - Delay Microseconds
;          - TotalTime(W) = [(1)+(2)+(1)+(W*3-1)+1+2] * (4/OSC) (This includes the movlw & the
;          call)
;          - Max Time When W=0xFF, [ 771 Cycles * (4/OSC) ]
;          - Must Declare COUNTER AS GPR
;          - W > 0
;*****
DELAYUS
    movwf   COUNTER

LOOP1
    decfsz  COUNTER,F
    goto    LOOP1
    nop
    return

;*****
;EEPROM - CALFLAGADR - Contains Calibration Flag Value
;          - CALVALADR - Contains Calibration Value
;*****
    ORG     (0X2100+CALFLAGADR)

    DE      0A5H           ;Initialize Calibration Flag

    DE      000H           ;Initialize Calibration Value

    END
```



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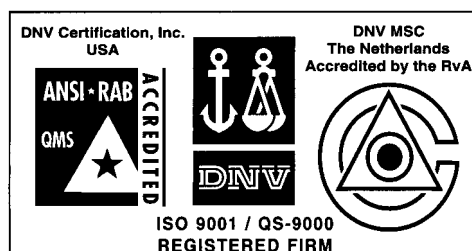
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