INTRODUCTION

As the demand for Graphical Embedded Applications becomes more popular, so does the need for developing cost effective solutions. Today, many companies offer solutions involving an additional internal or external graphics controller as part of a system, which may result in higher costs and more complicated designs. In most cases, for a simple embedded Graphical User Interface (GUI), these graphics controllers are not necessary, but a suitable solution may not be available. One solution that is becoming more popular is to use a controllerless solution. This solution uses microcontroller peripherals to create a "virtual" graphics controller for graphics rendering without taking up large amounts of CPU time (in this solution less than 5%).

The Low-Cost Controllerless Graphics PiCtail™ Plus Daughter Board (referred to as the LCC Graphics Board), was designed to showcase a technique offered by Microchip that utilizes this low-cost controllerless method and is designed to work with many existing PIC32 starter kits.

This application note describes the LCC Graphics Board that enables the implementation of a low-cost controllerless graphic method using a PIC32 microcontroller.

Basic Graphics Definitions

Pixel – One dot of color data on a LCD.

Refresh Rate — Defined in Hertz (Hz), the rate at which the LCD panel frame is being redrawn per second.

Resolution – Defined in horizontal by vertical dimensions, the number of pixels a certain display panel contains. For example, a QVGA LCD panel that is 320x240 pixels has a horizontal pixel count of 320 and a vertical pixel count of 240.

Pixel Clock (PCLK) – LCD panels use this signal to synchronize the sampling of incoming color data. The clock signal needs to be faster for higher resolutions so that all pixels of a frame can be clocked.

Frame Buffer – Volatile memory where pixel color data is stored for the purposes of refreshing an LCD screen of a certain resolution.

Pixel Throughput – Speed at which a pixel can be redrawn. The time to draw an entire frame would be pixel throughput multiplied by the LCD screen resolution.

Color Depth – Defines how many possible colors a pixel can be drawn. Commonly represented in bits per pixel (BPP), a common color depth is 16 BPP, where the color data is represented in a 565 RGB color format. In this format, 565 represents 5 red, 6 green, and 5 blue color bits.
SETTING UP A CONTROLLERLESS GRAPHICS SYSTEM

In general, a controllerless graphics system needs to send a frame of pixel information to a display glass at a certain rate. This refresh rate is usually around 60 Hz. To do this, the system must constantly send frame data to the LCD panel. At first inspection, it seems like this task would take up most of the CPU time in an MCU. However, this is not the case for PIC32 MCUs that contain a Direct Memory Access (DMA) peripheral for data transfer. With a DMA transferring the pixel data, less than 5% of CPU time can be used to achieve a "virtual" graphics controller.

PIC32 MCUs have a built-in DMA peripheral. This peripheral can transfer data from one location to another without CPU intervention. In a controllerless graphics method, the DMA is set up to transfer one line of frame data at a time through the Parallel Master Port (PMP). Each line consists of many pixels. The DMA sends a portion of the frame buffer during one transfer. A PMP or Timer interrupt request is used to trigger the next DMA transfer until a line is transferred. In PIC32 devices with non-persistent interrupts, a timer is used as the DMA trigger source.

During data transfers, the PMP strobes a read or write signal after each pixel transfer. The read/write strobes of the PMP peripheral act as the pixel clock for the display glass. After each line of pixel data is transferred, the CPU is interrupted by the DMA and certain timing signals (e.g., HSYNC, VSYNC, and DEN) necessary for LCD panels are updated. This is repeated continuously until an entire frame has been drawn. The frame is stored in volatile memory so the image can be dynamic. In this setup, SRAM memory is used. This configuration is the foundation for a controllerless graphics system. The system can be set up to use internal SRAM memory or external SRAM memory. The system diagram is illustrated in Figure 1 and Figure 2.

Mapping color to an TFT LCD display is done by using the PMP data lines. Depending on the color format used, the 16 PMP data lines can be configured to transmit the color data. In 8 BPP Color mode only eight PMP data lines are needed. When using external memory for 16 BPP Color mode, eight or 16 PMP data lines can be used. If eight data lines are used, the external memory data lines still get mapped to the TFT LCD in 16 BPP mode; however, the PIC32 MCU only connects to the memory through eight bits. When a write needs to be performed, the PIC32 MCU can then use the low/high byte pins on the external memory to send 16-bit color values to the SRAM.
DMA AND PMP INITIALIZATION
ROUTINE

Code to set up and initialize the DMA and PMP is provided in Example 1. This code is a snippet from the LCC driver software, and is being provided as a reference to show how easy it is to set up a system for controllerless graphics. It is not intended for copy and reuse purposes.

EXAMPLE 1: DMA AND PMP INITIALIZATION SOURCE CODE

```c
//Suspend ALL DMA transfers
DMACONbits.SUSPEND = 1;

#define PMP_CONTROL
(PMP_ON|PMP_MUX_OFF|PMP_READ_WRITE_EN|PMP_CS2_EN|PMP_CS2_POL_LO|PMP_WRITE_POL_LO|PCLK_POLARITY)

#define PMP_MODE
(PMP_DATA_LENGTH|PMP_MODE_MASTER2|PMP_WAIT_BEG_1|PMP_WAIT_MID_1|PMP_WAIT_END_1)

// Set up the PMP
// PMP is setup to use data and address lines, in 16 bit PMP mode
// PMP wait states are set to fastest
mPMPopen(PMP_CONTROL, PMP_MODE, PMP_ADDRESS_LINES, PMP_INT_ON);

// Set PMP address to 0
PMADDR = 0x0000;

// Open the desired DMA channel
DmaChnOpen(1, 0, DMA_OPEN_DEFAULT);

// Set the transfer event control: what event is to start the DMA transfer
DmaChnSetEventControl(1, DMA_EV_START_IRQ(_TIMER_2_IRQ));

// Set the transfer parameters: source & destination address, source & destination size,
// number of bytes per event source is the PMP, destination is a dummy array, source size is
// 2 for 16-bit color, first destination size is the backporch, transfers per event is two.
DmaChnSetTxfer(1, (void*)&PMDIN ,&GraphicsFrame[0] , 2, HBackPorch, 2);

// Set INT controller priority to 7 for highest priority
INTSetVectorPriority(INT_VECTOR_DMA(1), INT_PRIORITY_LEVEL_7);

// Set INT controller sub-priority
INTSetVectorSubPriority(INT_VECTOR_DMA(1), INT_SUB_PRIORITY_LEVEL_3);

// Enable the transfer done interrupt, when all buffer transferred
DmaChnSetEvEnableFlags(1, DMA_EV_BLOCK_DONE);

// Enable the interrupt in the INT controller
INTEnable(INT_SOURCE_DMA(1), INT_ENABLED);

// Once configured, enable the DMA channel
DmaChnEnable(1);

// Turn on Timer2 to act as a "trigger" for the pixel clock (DMA transfer)
OpenTimer2(T2_ON | T2_SOURCE_INT | T2_PS_1_1, 10);

// Start ALL DMA transfers
DMACONbits.SUSPEND = 0;
```
BASICS OF THIN-FILM TRANSISTOR (TFT) LCD PANELS

There are different types of LCD glass to choose from in the marketplace. The controllerless graphics method was designed to work with TFT LCD panels, but can work with CSTN or MSTN glass with minor modifications. Figure 3 shows a typical timing of a TFT display panel.

The data lines consist of the pixel color information. Most LCD panels can have 8 to 24 color data lines depending on the color depth of the LCD panel. These data lines supply the LCD panel with the raw color data of each pixel.

The clock signals HSYNC, VSYNC, DEN and PCLK are used to synchronize the pixel data with the graphics frame and the LCD panel. The sync lines tell the LCD panel when the data is at the start or end of a line (HSYNC) or a frame (VSYNC). The DEN, or data enable line, lets the LCD panel know when valid pixel data is being sent to the LCD panel. The DEN is required for TFT type LCD panels because there is time required to set up the LCD panel for proper pixel locations. This setup time is shown in Figure 3 as the gray non-display area. The Microchip logo represents the area of the timing where valid pixel data needs to be sent to the screen. This is where the DEN is asserted high. Data is sent one line at a time until the entire frame is drawn. The PCLK signal is not shown, but is the clock source for the whole system. One clock pulse from the PCLK updates the LCD panel. All other clock lines must be synchronized to the pixel clock to achieve proper image output. Not all display panels have HSYNC, VSYNC, and DEN lines. This application note covers panels that can be used to explain each line and its purpose. LCD panels not containing HSYNC and VSYNC signals can still be used with the controllerless graphics setup.

The LCC software driver is set up to help with synchronization needing certain timing parameters, such as pulse width, front porch, and back porch for both horizontal and vertical pulses. After these values are compiled into the LCC Graphics driver, the LCD Panel displays the frame. These timing constants can be found in the data sheet of the specific LCD Panel to be used. It is usually a value given in pixel clocks. These constants help set up the proper frequencies needed for accurate image data on the display.

FIGURE 3: CLOCK SIGNAL SETUP TIMES
**LCC GRAPHICS FLOWCHART**

Figure 4 shows what happens inside the PIC32 microcontroller when a graphics frame is being sent to the display. The DMA/PMP block indicates what the DMA and PMP peripherals that share the data bus with the CPU are performing. The CPU block indicates the tasks required for graphics rendering. The DMA Interrupt Service Routine (ISR) is the only code that must be written besides setting up the DMA and PMP peripherals to send a graphics frame to the display. This flowchart does not specify the location of the graphics frame (internal or external), and it does not describe updating the frame image.

**FIGURE 4: PIC32 MICROCONTROLLER LCC GRAPHICS FLOWCHART**

CPU loading is minimal as the only function the CPU is required to do is to update the timing signals and set up the next DMA transfer during the DMA ISR.

- **CPU**
  - Update Timing Signals
  - Set up Line Transfer

- **DMA ISR**
  - Update Timing Signals

- **DMA/PMP**
  - Send One Pixel of Frame Line of Data to the Screen from SRAM
  - Update Pixel Clock (PMP Read/Write Strobe)

- **Interrupt Trigger**

- **End of Line?**
  - Call DMA ISR
TIMING DIAGRAMS

Many questions come up as to how the whole system works. A good way to address these questions are by the use of what is produced at run-time. This can be seen in some of the timing diagrams that are created in the system. This section shows several different timing diagrams of the system, which demonstrates how low-cost controllerless graphics works.

Figure 5, shows the pixel clock that is generated by the PMP strobe (read or write). The pixel clock is required by the TFT LCD panels and the PIC32 device can generate signals up to 15 MHz, which is sufficient for WQVGA solutions. All timing diagrams were taken with a pixel clock of 13 MHz. To change the speed of the pixel clock, the system can slow down the PMP or DMA transfer speed. An SRAM with support for these pixel clocks must be considered. This signal can be seen by probing the SHIFT test point seen on most Microchip graphics display boards.

Figure 6 shows a typical frame rate of a graphics system. The frame rate is approximately 60 Hz, which is a typical refresh rate seen in today’s market. This signal can be seen by probing the FRAME test point on most Microchip graphics display boards.

FIGURE 5: CLEAN PIXEL CLOCK TIMING DIAGRAM

FIGURE 6: FRAME RATE TIMING DIAGRAM
Figure 7 shows a zoomed out pixel clock in external memory code. There are two areas in the diagram where the pixel clock is stopped. This is where the ISR is updating LCD timing constraints. This is the only portion of LCC that requires CPU bandwidth and remaining is handled by the DMA transfer. The delta ‘x’ shows how much time the ISR routine absorbs, which equates to 80 clock cycles. Therefore, if we consider a WQVGA display refreshing at 60 Hz, with 272 lines and two interrupts per line, the LCC solution only uses \((60 \times 272 \times 2 \times 80) = 2.6\) MIPS.

Figure 8 shows the affect of the putpixel function on the pixel clock. The putpixel function updates the frame and it is designed to update two frames per pixel halt. The total time required to update two pixels is 800 ns. The user can change the software to monitor the update rate so that the refresh rate does not fall below a certain refresh (50 Hz).
**RENDERING NEW PIXELS ON THE FRAME**

Rendering new pixels in the screen is as important as refreshing the screen. This is performed by the CPU writing to the display buffer. If the frame is stored externally, the DMA transfer is suspended while the frame is being updated. This is necessary because there is only one PMP peripheral and it is being shared by the “virtual” graphics controller or DMA transfer. This method does affect the refresh rate of the screen. The amount of pixel updates needs to be monitored to prevent too large of a refresh rate change; otherwise, the change will be perceptible by the human eye. This is done by using a pixel count variable within the virtual graphics controller that is updated on every pixel write and cleared during every DMA interrupt.

**HARDWARE DESCRIPTION**

The LCC Graphics Board is built with simplicity and low cost in mind. The onboard 512 Kbyte SRAM IC is only required if the application is using the LCC Graphics Board for external memory. Otherwise, if a PIC32 MCU with enough internal memory is used with the board, no external memory is necessary. The equation to calculate whether a certain PIC32 MCU has enough volatile memory to store a data frame is provided in Equation 1.

In the following example, the internal memory demo for the LCC Graphics Board uses a starter kit that has a PIC32MX795F12L device, which has 128 Kbytes of SRAM. The demonstration uses QVGA resolution and 8 BPP Graphics; therefore, the equation is:

\[
76,800 = 320 \times 240 \times 1
\]

This technique still leaves almost half of the internal SRAM for program use, while giving the designer 255 color choices to create a meaningful embedded user interface application.

If extra memory is needed, there are many different types to choose from. A parallel SRAM was used for this board, but any type of volatile memory can be used, as long as it is fast enough to support the required frame rate.

PSRAM is a cost-effective external memory that offers a lower cost than SRAM; however, this type of memory has slower access speeds.

There are 15 jumpers on the LCC Graphics Board to change from Internal Memory mode to External Memory mode. Set jumper pins 1 and 2 when using internal SRAM and set jumper pins 2 and 3 when using external SRAM.

The LCC Graphics Board was made to be used with many different PIC MCUs. The board provides a starter kit connector to connect starter kits, such as the PIC32 USB Starter Kit II, and a PICtail™ Plus connector to connect the board to an Explorer 16 Development Board.

Since LCC uses no graphics controller, this makes many graphics features available through software including alpha blending, scrolling, and the use of multiple frames. A user is no longer limited by the graphics controller used; instead, the PIC microcontroller is used.

**EQUATION 1:**

\[
\text{SRAM size} = (x \text{ pixel resolution}) \times (y \text{ pixel resolution}) \times (\text{Bytes of Color Depth})
\]
Display Connector

LCD panels are connected to the display connector. Descriptions of each display connector pin are listed in Table 1.

**TABLE 1: DISPLAY CONNECTOR PINS**

<table>
<thead>
<tr>
<th>Pin Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RD9, RB0, RB9, RB1</td>
<td>4-wire Resistive Touch Screen Lines</td>
</tr>
<tr>
<td>R0-R4</td>
<td>Red Color Data Lines</td>
</tr>
<tr>
<td>G0-G5</td>
<td>Green Color Data Lines</td>
</tr>
<tr>
<td>B0-B4</td>
<td>Blue Color Data Lines</td>
</tr>
<tr>
<td>RC1/LCD_RESET</td>
<td>LCD Reset Line</td>
</tr>
<tr>
<td>RC2/LCD_CS</td>
<td>LCD Chip Select Line</td>
</tr>
<tr>
<td>SCK1, SD01, SDI1, SS1</td>
<td>SPI Lines for Communication for Timing or Touch Controllers</td>
</tr>
<tr>
<td>RBS/LCD_DC</td>
<td>LCD DC Power Enable Line</td>
</tr>
<tr>
<td>LCD_SHIFT</td>
<td>Pixel Clock</td>
</tr>
<tr>
<td>RD2/LCD_DEN</td>
<td>Data Enable (DEN) Line</td>
</tr>
<tr>
<td>RC3/VSYNC</td>
<td>VSYNC Line</td>
</tr>
<tr>
<td>RB8/HSYNC</td>
<td>HSYNC Line</td>
</tr>
<tr>
<td>PMPBE</td>
<td>Backlight Enable Line (PWM Capable)</td>
</tr>
</tbody>
</table>
SOFTWARE USAGE

The LCC Graphics Board uses the Microchip Graphics Library that makes creating a GUI such as the one presented in this application note fast and easy. The Microchip Graphics Library is available for download free-of-charge from the Microchip Libraries of Applications web page (www.microchip.com/MLA).

There are two methods to use software with the Graphics Library: internal SRAM memory and external SRAM memory.

The internal SRAM memory method uses the write strobe of the PMP for the pixel clock. Jumper rows 1 and 2 on the LCC Graphics Board must be set for this configuration. In this setup, all color is 8 BPP and no external SRAM is used. SRAM from inside the PIC32 MCU is continuously writing its pixel values to the PMP. For 8 BPP color, a 332 RGB color format is used (i.e., 3 color values for red, 3 for green, and 2 for blue). This is a common color format, because red is an easier color for the human eye to detect than blue.

The external SRAM memory method uses the read strobe of the PMP for the pixel clock. Jumper rows 2 and 3 on the LCC Graphics Board must be set for this configuration. In this setup, all color is 16 BPP and the external SRAM contains the graphics frame that is continuously being read. For 16 BPP color, a 565 RGB color format is used (i.e., 5 color values for red, 6 for green, and 5 for blue).

In both methods, when connecting to an LCD panel with more than 16 color lines, the unused color lines are tied to the Most Significant bits of the last color bit being used. This ensures that a full color scale from white to black can be achieved.

DEMONSTRATION SOFTWARE

Demonstration software specifically for the LCC Graphics Board is available on the LCC Graphics web page at www.microchip.com. The demonstration showcases both internal and external memory methods and contains many different user interface screens that can be created by using the microchips Graphics Library and Microchip’s Graphics Display Designer. Other software for the LCC Graphics Board is contained within the Microchip’s Graphics Library, where the LCC graphics driver is contained, which is able to run most of the demonstrations found in the Microchip Graphics Library.

CONCLUSION

This application note describes the Low-Cost Controllerless (LCC) Graphics PICtail Plus Daughter Board, which can be used to enable the implementation of a low-cost controllerless graphics system using a PIC32 microcontroller.

REFERENCES

- Microchip Libraries of Applications: www.microchip.com/MLA
- PIC32 Device Family: www.microchip.com/PIC32
- Microchip Graphics Support: www.microchip.com/graphics
APPENDIX A: SOURCE CODE

Software License Agreement

The software supplied herewith by Microchip Technology Incorporated (the "Company") is intended and supplied to you, the Company's customer, for use solely and exclusively with products manufactured by the Company.

The software is owned by the Company and/or its supplier, and is protected under applicable copyright laws. All rights are reserved. Any use in violation of the foregoing restrictions may subject the user to criminal sanctions under applicable laws, as well as to civil liability for the breach of the terms and conditions of this license.

THIS SOFTWARE IS PROVIDED IN AN "AS IS" CONDITION. NO WARRANTIES, WHETHER EXPRESS, IMPLIED OR STATUTORY, INCLUDING, BUT NOT LIMITED TO, IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE APPLY TO THIS SOFTWARE. THE COMPANY SHALL NOT, IN ANY CIRCUMSTANCES, BE LIABLE FOR SPECIAL, INCIDENTAL OR CONSEQUENTIAL DAMAGES, FOR ANY REASON WHATSOEVER.

All of the software covered in this application note is available as a single WinZip archive file. This archive can be downloaded from the Microchip corporate Web site at:

www.microchip.com
APPENDIX B: REVISION HISTORY

Revision A (July 2011)
This is the initial released version of this document.

Revision B (October 2012)
This revision includes the following updates:
• The “Board Setup” section, including Figure 1 was removed
• A paragraph was added to "Setting up a Controllerless Graphics System"
• A sentence referencing PSRAM was added to "Hardware Description"
• Figure 9: “Display Connector Schematic” was removed
• Appendix B “Schematics” was removed
• Additional minor updates to text and formatting were incorporated throughout the document
Note the following details of the code protection feature on Microchip devices:

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip’s Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
- Neither Microchip nor any other semiconductor manufacturer can guarantee the security of their code. Code protection does not mean that we are guaranteeing the product as “unbreakable.”

Code protection is constantly evolving. We at Microchip are committed to continuously improving the code protection features of our products. Attempts to break Microchip’s code protection feature may be a violation of the Digital Millennium Copyright Act. If such acts allow unauthorized access to your software or other copyrighted work, you may have a right to sue for relief under that Act.

Information contained in this publication regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer’s risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights.

Trademarks
The Microchip name and logo, the Microchip logo, dsPIC, FlashFlex, KEELoo, KEELoo logo, MPLAB, PIC, PICmicro, PICSTART, PIC32 logo, rPIC, SST, SST Logo, SuperFlash and UNI/O are registered trademarks of Microchip Technology Incorporated in the U.S.A. and other countries. FilterLab, Hampshire, HI-TECH C, Linear Active Thermistor, MTP, SEEVAL and The Embedded Control Solutions Company are registered trademarks of Microchip Technology Incorporated in the U.S.A. Silicon Storage Technology is a registered trademark of Microchip Technology Inc. in other countries. Analog-for-the-Digital Age, Application Maestro, BodyCom, chipKIT, chipKIT logo, CodeGuard, dsPICDEM, dsPICDEM.net, dsPICworks, dsSPEAK, ECAN, ECONOMONITOR, FanSense, HI-TIDE, In-Circuit Serial Programming, ICSP, Mindi, MiWi, MPASM, MFP, MPLAB Certified logo, MPLIB, MPLINK, mTouch, Omniscient Code Generation, PICC, PICC-18, PICDEM, PICDEM.net, PICkit, PICtail, REAL ICE, rLAB, Select Mode, SQI, Serial Quad I/O, Total Endurance, TSHARC, UniWinDriver, WiperLock, ZENA and Z-Scale are trademarks of Microchip Technology Incorporated in the U.S.A. and other countries. SQTP is a service mark of Microchip Technology Incorporated in the U.S.A. GestIC and ULPP are registered trademarks of Microchip Technology Germany II GmbH & Co. & KG, a subsidiary of Microchip Technology Inc., in other countries. All other trademarks mentioned herein are property of their respective companies.

© 2011-2012, Microchip Technology Incorporated, Printed in the U.S.A., All Rights Reserved.

QUALITY MANAGEMENT SYSTEM CERTIFIED BY DNV

ISO/TS 16949

Microchip received ISO/TS-16949:2009 certification for its worldwide headquarters, design and wafer fabrication facilities in Chandler and Tempe, Arizona; Gresham, Oregon and design centers in California and India. The Company’s quality system processes and procedures are for its PIC® MCUs and dsPIC® DSCs, KEELoo® code hopping devices, Serial EEPROMs, microperipherals, nonvolatile memory and analog products. In addition, Microchip’s quality system for the design and manufacture of development systems is ISO 9001:2000 certified.