

Using a Timer to Interface PIC18 MCUs with UNI/O[®] Bus-Compatible Serial EEPROMs

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INTRODUCTION

As embedded systems become smaller, a growing need exists to minimize I/O pin usage for communication between devices. Microchip has addressed this need by developing the UNI/O[®] bus, a low-cost, easy-to-implement solution requiring only a single I/O pin for bidirectional communication.

UNI/O bus-compatible serial EEPROMs can be used to enhance any application facing restrictions on available I/O. Such restrictions can potentially stem from connectors, board space or from the master device itself.

The 11XXX family is the newest addition to Microchip Technology's broad serial EEPROM product line, and is compatible with the newly developed UNI/O bus.

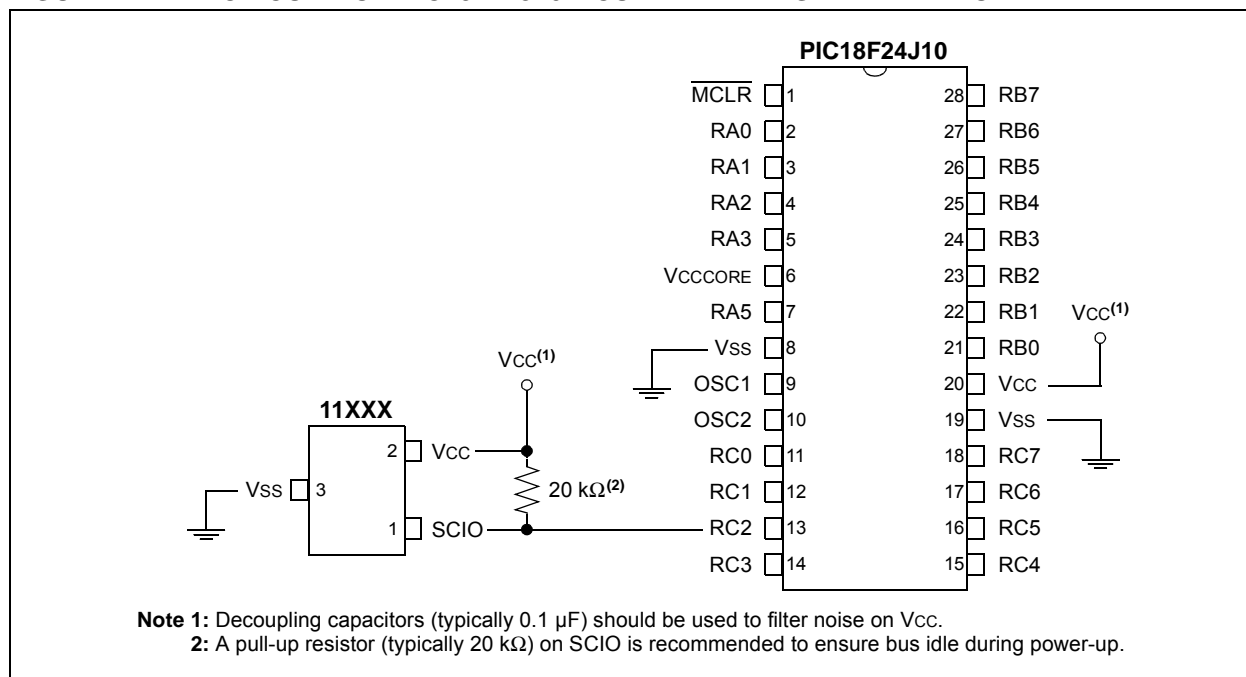
The main features of 11XXX serial EEPROMs are:

- Single I/O pin used for communication
- EEPROM densities from 1 Kbits to 16 Kbits
- Extremely small packages
- Bus speed from 10 kHz up to 100 kHz
- Voltage range from 1.8V to 5.5V
- Low-power operation
- Temperature range from -40°C to +125°C
- Over 1,000,000 erase/write cycles

This application note is part of a series that provides source code to help the user implement the protocol with minimal effort.

Figure 1 is the hardware schematic that depicts the interface between the Microchip 11XXX series of UNI/O bus-compatible serial EEPROMs and Microchip's PIC18 family of MCUs. The schematic shows the connections necessary between the MCU and the serial EEPROM as tested. The software was written assuming these connections. The single I/O connection between the MCU and the serial EEPROM includes a recommended pull-up resistor. A decoupling capacitor across Vcc and Vss is also recommended.

FIGURE 1: CIRCUIT FOR PIC18F24J10 MCU AND 11XXX SERIAL EEPROM



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FIRMWARE

The purpose of the firmware is to show how to generate specific UNI/O bus transactions using a generic I/O pin on the microcontroller. The focus is to provide the user with a strong understanding of communication with the 11XXX series serial EEPROMs, thus allowing for more complex programs to be written in the future.

The firmware was written in assembly language using MPASM™ assembler and MPLINK™ linker. Both the MPASM assembler and the MPLINK linker come with the installation of MPLAB® IDE. The firmware was written using the MPLAB IDE.

Bus speed and digital I/O assignments are inputs required from the user. Most of the complex tasks have been done in the firmware and the user is not expected to write any low-level subroutines.

The firmware was tested with $F_{osc} = 20$ MHz and $F_{bus} = 50$ kHz using the 11XXX serial EEPROM and the PIC18F24J10 MCU. The 11XXX serial EEPROM has a page size of 16 bytes.

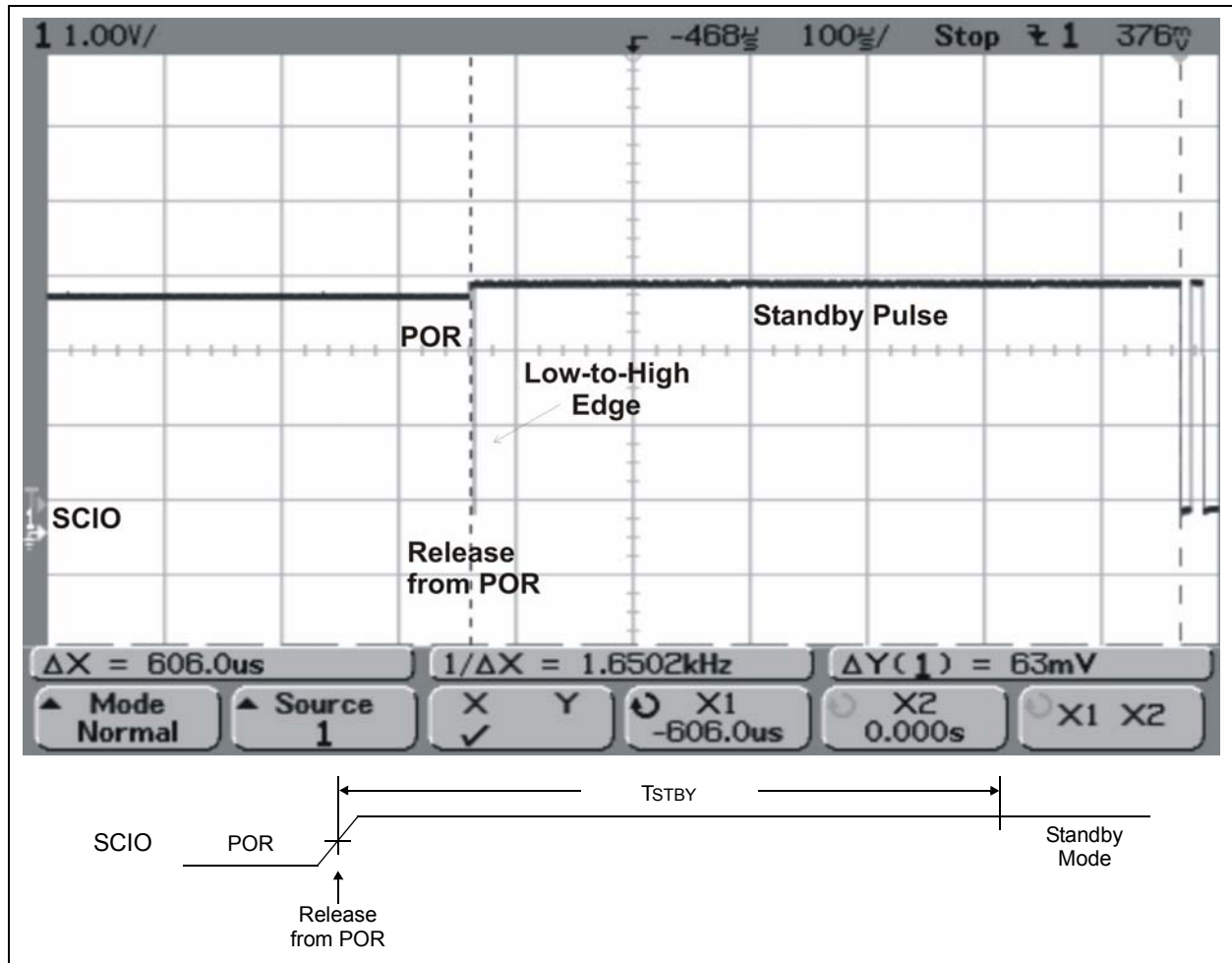
Oscilloscope screen shots are shown in this application note to assist in better understanding UNI/O bus transactions.

INITIALIZATION

Before initiating communication with the serial EEPROM, the master device (MCU) must generate a low-to-high edge on the SCIO to release the serial EEPROM from Power-on Reset (POR). Because bus idle is high, the MCU must create a high-low-high pulse on the SCIO. Once the serial EEPROM has been released from POR, a standby pulse with a minimum timing of T_{STBY} is performed to place the serial EEPROM into Standby mode, as shown in Figure 2.

Note that once a command has successfully executed – indicated by the reception of a Slave Acknowledgment (SAK) following the No Master Acknowledgment (NoMAK) – the serial EEPROM enters Standby mode immediately and a standby pulse is not necessary. In this case, only the start header setup time (T_{SS}) must be observed before the MCU may initiate another command to the same device.

FIGURE 2: STANDBY PULSE



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WRITE ENABLE

Before a write operation to the array or the STATUS register can occur, the Write Enable Latch (WEL) bit must be set. This is done by issuing a Write Enable (WREN) command.

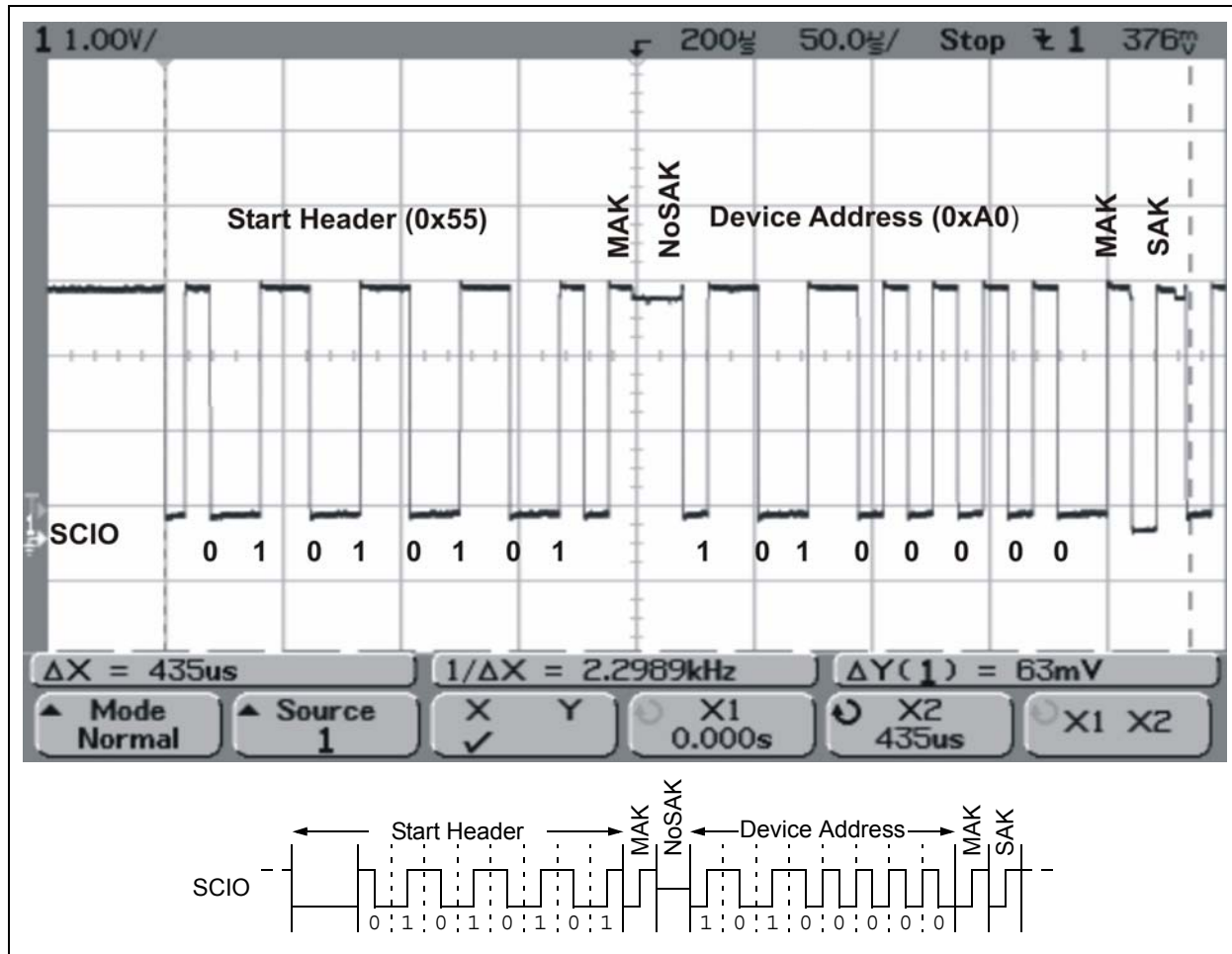
The WEL bit can be cleared by issuing a Write Disable (WRDI) command. It is also cleared upon termination of a write cycle to either the array or the STATUS register, and upon POR.

The write enable operation consists of the following components: the start header, which is followed by the device address and the command byte.

Start Header and Device Address

To issue a WREN command, the MCU transmits the start header. This consists of a low pulse (THDR) followed by '01010101', and a Master Acknowledge (MAK) followed by a NoSAK. Next, the MCU transmits the device address ('10100000') and another MAK. The serial EEPROM then responds with a SAK if the start header and device address were received correctly. Figure 3 shows the details of the start header and the device address.

FIGURE 3: START HEADER AND DEVICE ADDRESS

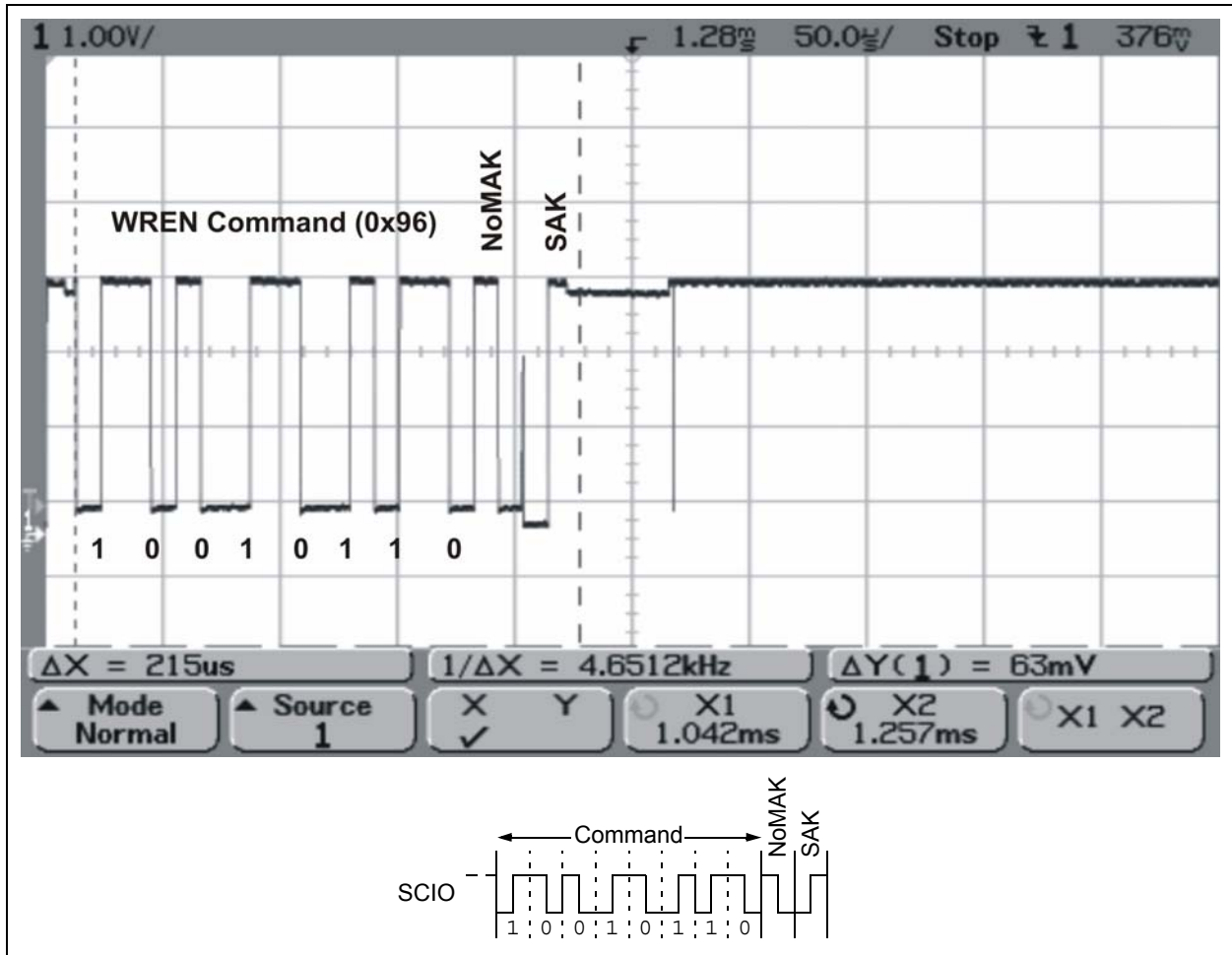


Write Enable (WREN) Command Byte

Once the SAK is received following the device address, the MCU sends the WREN command ('10010110' or 0x96) and performs a final Acknowledge sequence. During this last sequence, the MCU sends a NoMAK to signal the end of the operation. Once again, the serial EEPROM responds with a SAK, indicating it received the byte successfully.

Figure 4 shows an example of the WREN command.

FIGURE 4: WRITE ENABLE COMMAND



PAGE WRITE

Once the WREN command has been performed, a page write operation can be executed to write data to the array. The serial EEPROM features a 16-byte page, so up to 16 bytes of data can be written within a single operation.

The page write operation consists of the following components: the write command, followed by the word address and the data bytes. Note that the start header and device address are not illustrated in this section but are still required to initiate the operation.

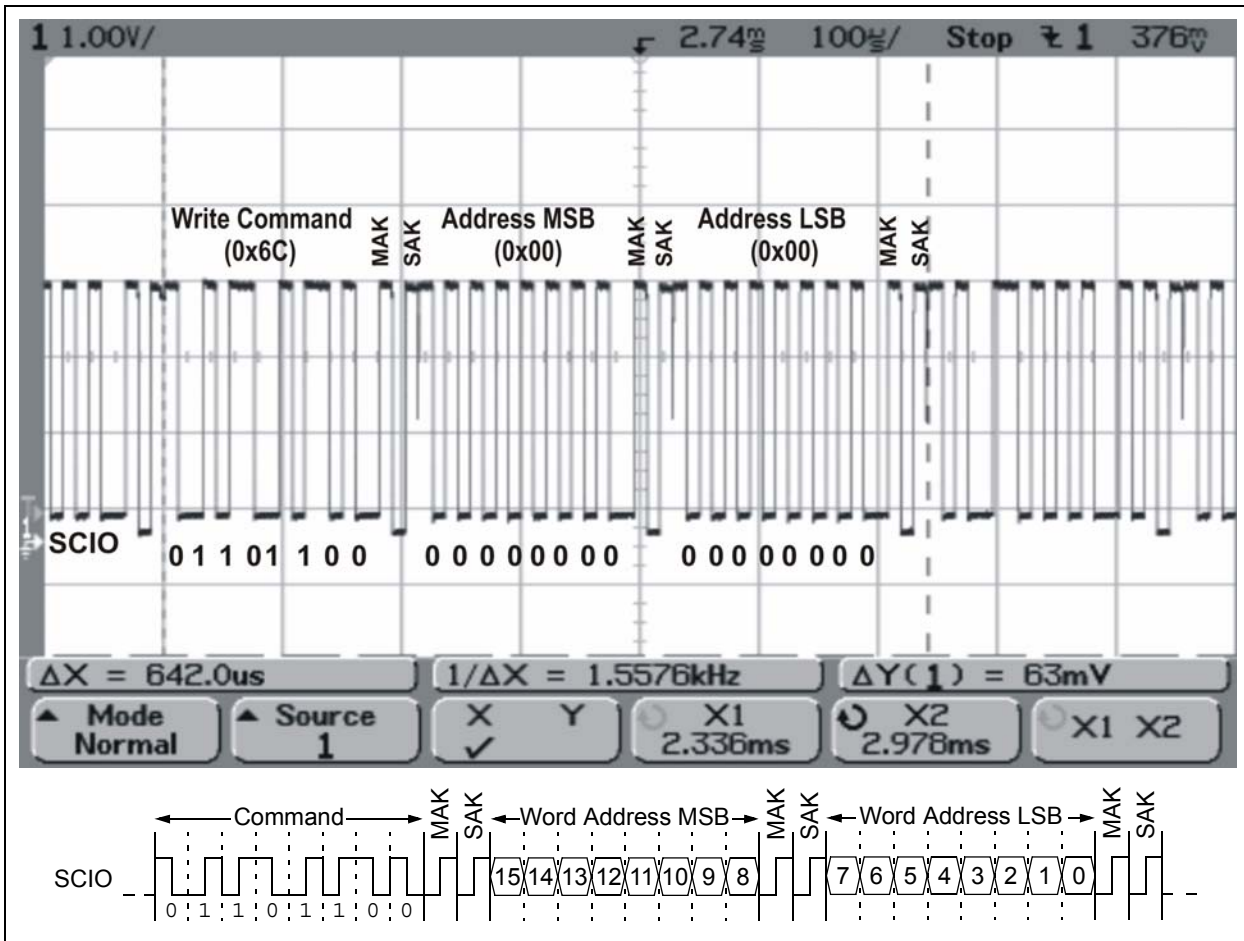
Before beginning the write command, a period of T_{ss} must be observed following the WREN command. This period can be used in place of the standby pulse after a command has been executed successfully when addressing the same serial EEPROM. After the T_{ss} period, the start header and device address are transmitted, as described in “**Start Header and Device Address**”.

Write Command and Word Address

After the start header and device address have been sent, the MCU transmits the write command ('01101100' or 0x6C) and the word address. The serial EEPROM uses a 16-bit word address to access the array, so two bytes must be transmitted for the entire word address, with the Most Significant Byte sent first. After every byte, the MCU transmits a MAK and the serial EEPROM responds with a SAK.

Figure 5 shows an example of the write command and the word address.

FIGURE 5: WRITE COMMAND AND WORD ADDRESS



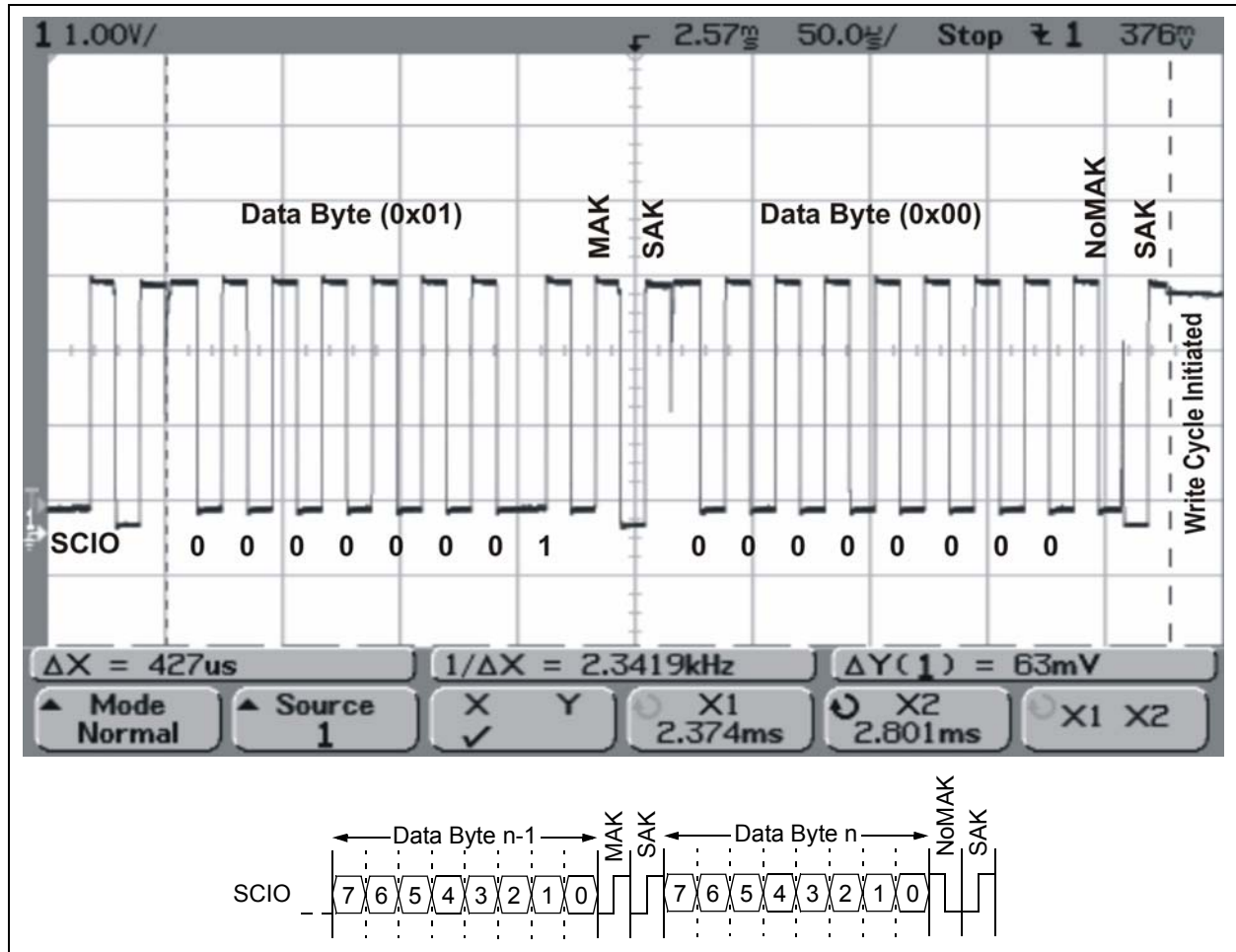
Data Bytes

Once the word address has been transmitted and the last SAK has been received, the data bytes can be sent. Up to 16 bytes of data can be sent within a single operation. After each byte is transmitted, the MCU sends a MAK and the serial EEPROM responds with a SAK if there are no errors. If at any point a NoSAK is received, indicating an error occurred, the operation must be restarted beginning with a standby pulse.

Once all data bytes have been sent, the MCU terminates the command by generating a NoMAK in place of the MAK, and the serial EEPROM again responds with a SAK. This also initiates the internal write cycle (T_{wc}).

Figure 6 shows the final data bytes sent by the MCU, as well as the NoMAK and SAK.

FIGURE 6: WRITE COMMAND FINAL TWO DATA BYTES



WRITE-IN-PROCESS POLLING

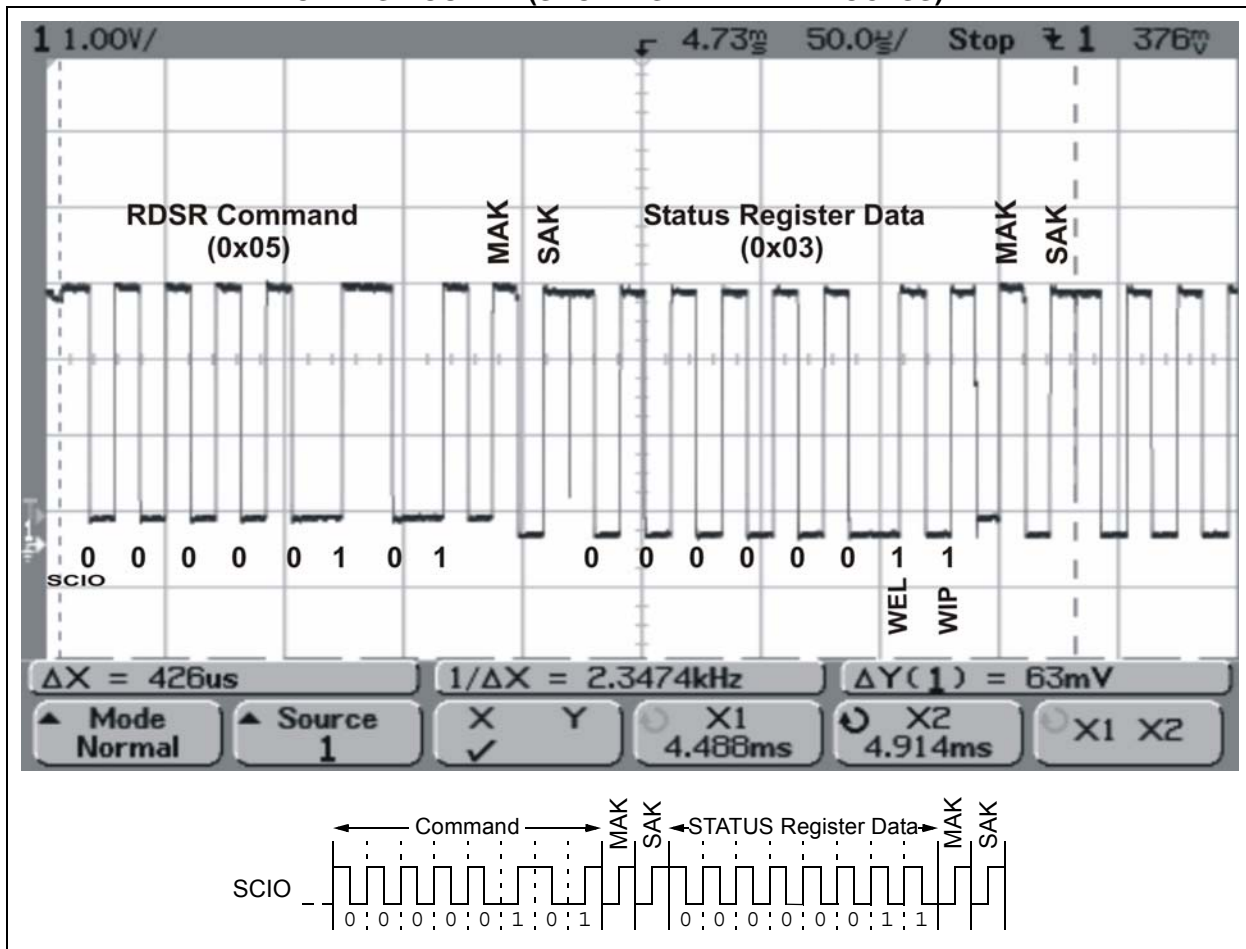
After an array or STATUS register WRITE instruction is executed, the MCU must observe a write cycle time (T_{wc}). Write cycle time is a maximum, so the actual time required is typically less. Therefore, to transfer data as efficiently as possible, using the Write-In-Process (WIP) polling feature is highly recommended. Because the STATUS register can be read during a write cycle, the WIP bit can be continuously monitored to determine the completion of the write cycle.

Write-In-Process Polling Routine

The process of WIP polling consists of the MCU sending a start header and device address after observing the T_{ss} period. The MCU follows this by sending the Read Status Register (RDSR) command ('00000101' or 0x05). After sending the subsequent SAK, the serial EEPROM transmits the STATUS register. At this point, the STATUS register can be requested again by sending a MAK. The WEL and WIP values sent are updated dynamically, so the MCU can continuously check the STATUS register. Sending a NoMAK terminates the command.

Figure 7 shows an example of WIP polling to check if a write operation has finished. In this example, the WIP bit is set ('1'), indicating that the write cycle has not yet completed.

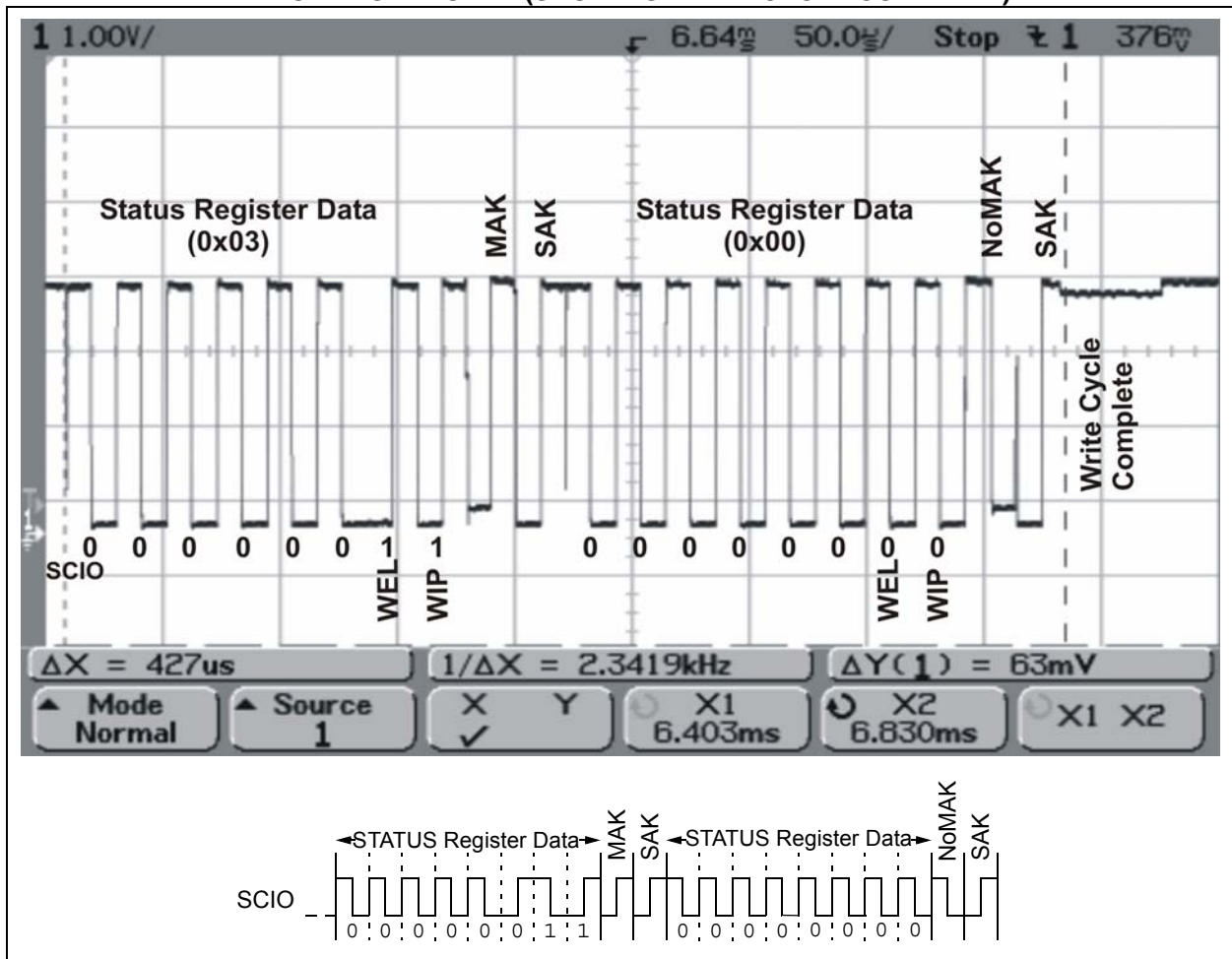
FIGURE 7: WIP POLLING ROUTINE (SHOWING WRITE-IN-PROCESS)



WIP Polling Complete

Figure 8 shows the final read of the STATUS register after the page write operation, in which the WIP bit is clear ('0'). This indicates that the write cycle is complete and the serial EEPROM is ready to continue.

FIGURE 8: WIP POLLING FINISHED (SHOWING WRITE CYCLE COMPLETE)



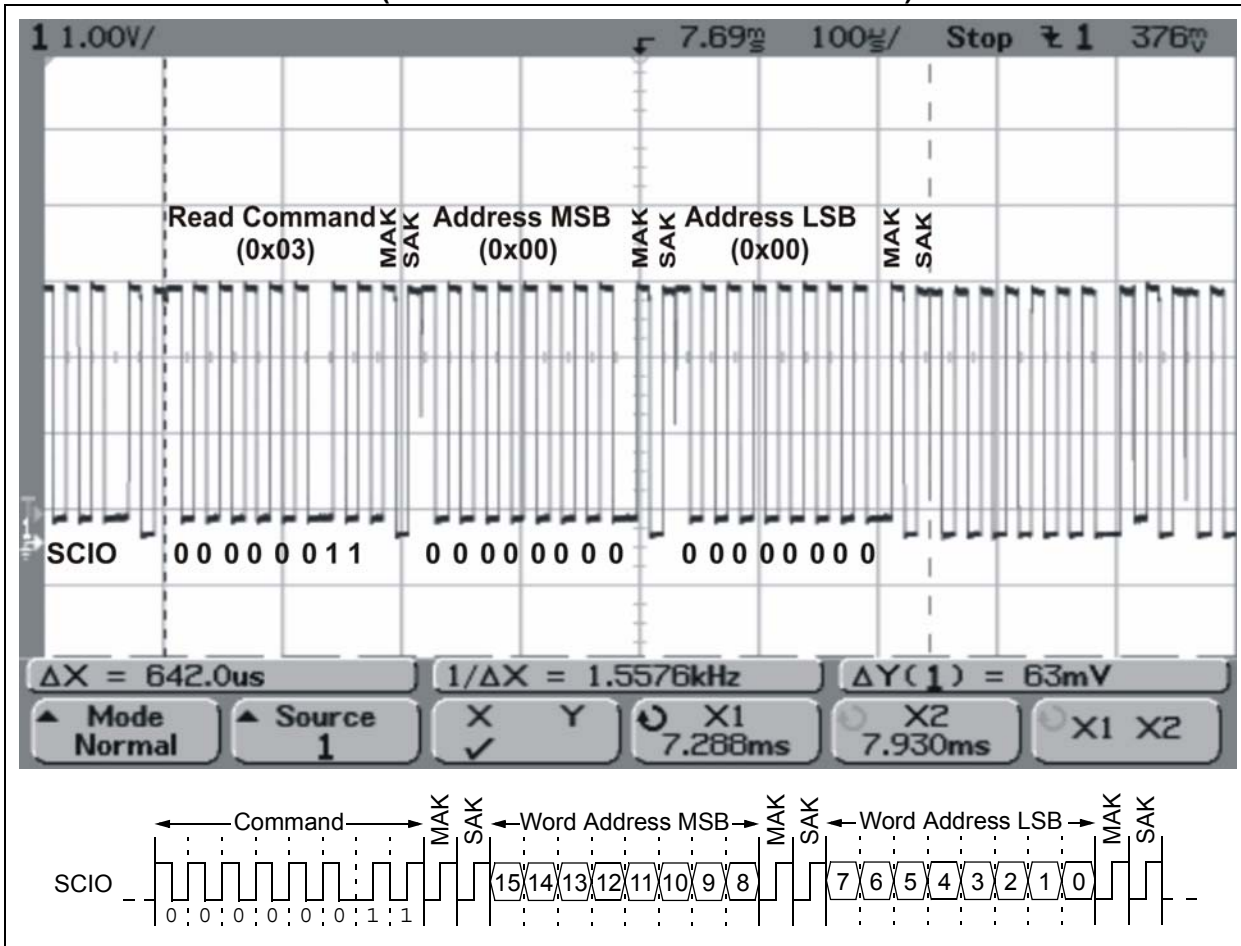
PAGE READ

The serial EEPROM allows data to be read from the array in a random access manner. Reading data from the array is very similar to the write operation, except that the Read is not limited to a single page. In order to read from the array, the start header and device address must first be sent after observing the T_{ss} period. The read command byte and word address bytes are transmitted next. The MCU generates a MAK after every byte, and the serial EEPROM responds with a SAK if no errors occurred.

Command and Word Address for Read

Figure 9 shows an example of the read command ('00000011' or 0x03) followed by the word address.

FIGURE 9: PAGE READ (COMMAND BYTE AND WORD ADDRESS)



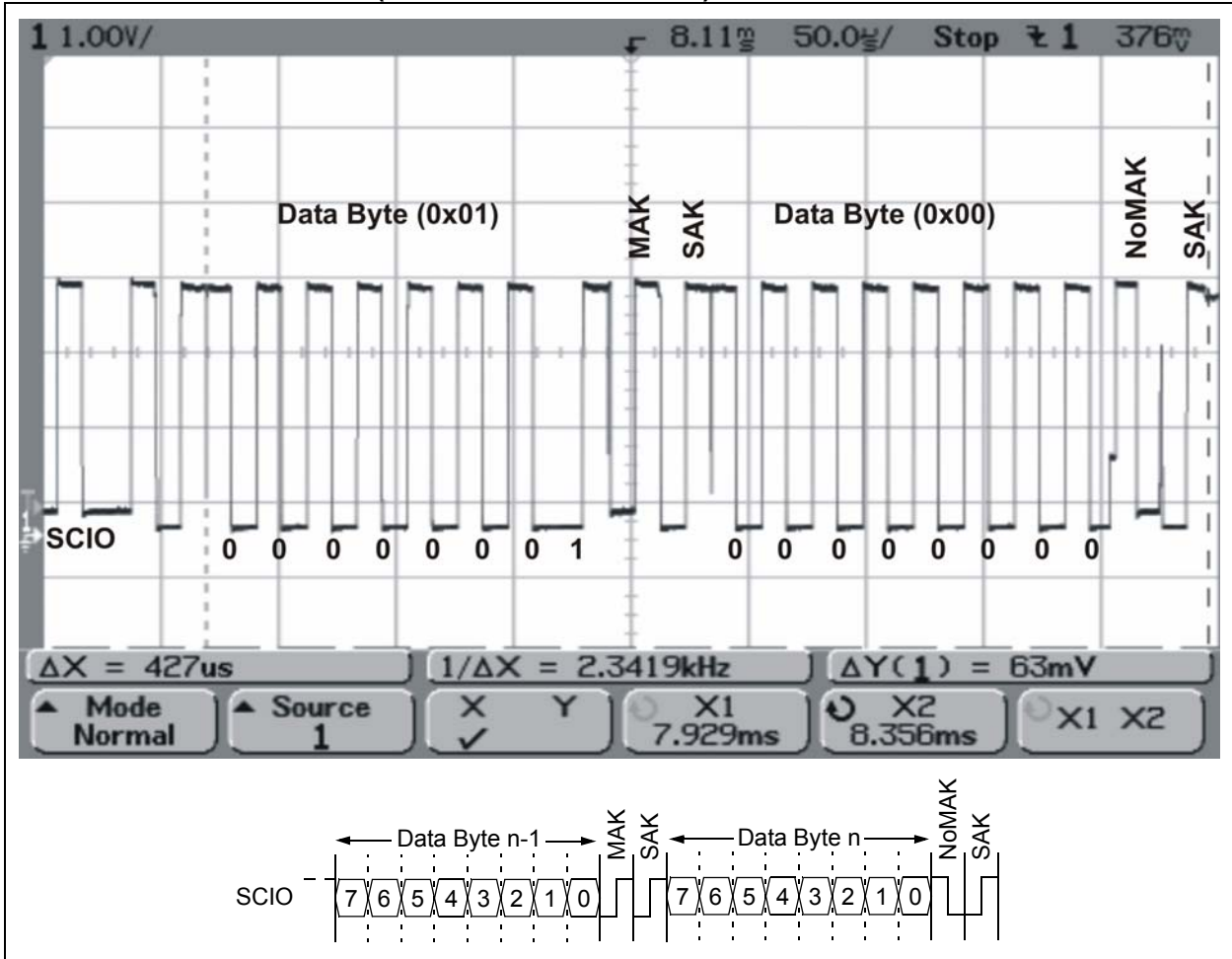
Reading Data Back

After the read command and word address have been sent and acknowledged, the serial EEPROM sends the first data byte from the array, starting at the address specified. In order to continue the read, the MCU must send a MAK after each data byte, with the serial EEPROM responding with a SAK if there are no errors. After each data byte has been sent, the serial EEPROM automatically increments the internal word address to output the next data byte.

The read operation is not limited to a single page, so the entire array can be read within a single operation if the MCU continues to request data. At the end of the array, the internal word address is automatically reset back to 0x000. A NoMAK terminates the operation.

Figure 10 shows the MCU reading the final two bytes of data. The MCU sends a NoMAK after the last byte to indicate that no more data is requested and to terminate the command.

FIGURE 10: PAGE READ (FINAL TWO DATA BYTES)



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CONCLUSION

This application note offers designers a set of firmware routines to access UNI/O serial EEPROMs using a generic I/O pin on the MCU. All routines were written in assembler for a PIC18 based MCU.

The code generated for this application note was tested using the PICDEM™ HPC Explorer Board (Part Number DM183022) with the PIC18F24J10 MCU using the schematic shown in Figure 1.

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