

## Adaptive Digital Line Length Tracking

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### INTRODUCTION

Despite the rapid advancement of digital TV, analog TV remains dominant for both transmission and display. Analog video formats, like digital formats, have precise specifications for how to format video. These specifications include how the luma, chroma, and synchronization information is packaged to provide the line, field, and frames of video information that recreate the images observed on TV screens. To display the video information accurately, each of these components must be correctly extracted from the video signal. Similarly, the timing and phase information must be maintained or recreated as it was when the video signal was first encoded at the source.

This application note outlines the challenges encountered when decoding and restoring a correct time base to nonstandard input video sources. This technology is known as Adaptive Digital Line Length Tracking (ADLLT™).

### NOISE-INDUCED TIME-BASE INACCURACIES

Video signals consist of various components, some of which can be altered or corrupted within the transmission path, resulting in distortion of some video package aspects. For RF transmitted signals, the synchronization information is normally present on the recovered signal, but its detection and extraction can be difficult or impossible because of excessive noise. It is important to note that even when recovering the synchronization is possible, its detection can be offset due to noise, which in turn introduces jitter on the recovered synchronization information.

Figure 1 shows a representation of a typical stream of line synchronization information. Figure 2 shows that slicing the synchronization information from this stream results in a stable video display.

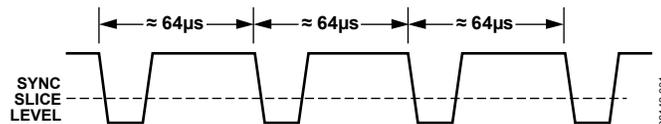


Figure 1. Line Synchronization Stream Without Noise at Source

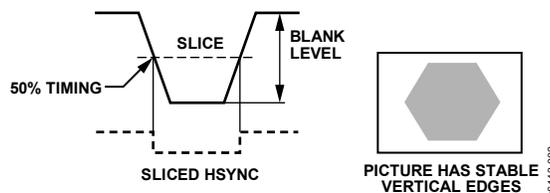


Figure 2. Stable Synchronization Extraction with No Vertical Jitter on Displayed Image

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**REVISION HISTORY**

7/06—Revision 0: Initial Version

Figure 3 is a representation of how noise can distort the synchronization information, resulting in a misinterpretation of the synchronization. Figure 3 shows the resulting stripped synchronization that can result from the noise. Note that the time base is corrupted and jitter introduced. The effect of this jitter on the displayed video is serrations at the start and end of each line (see Figure 4).

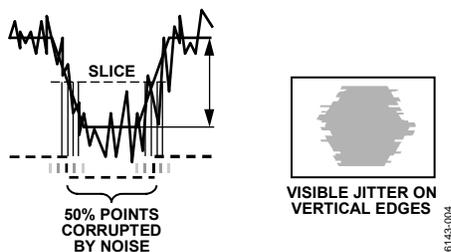


Figure 3. Noisy Synchronization Information Resulting in Extracted Synchronization Jitter

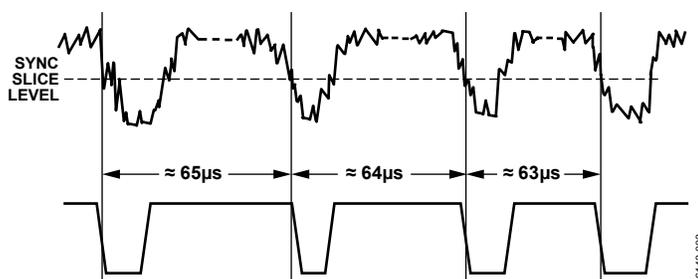


Figure 4. HSYNC Jitter Resulting in Line-to-Line Shifting of Displayed Image

A typical noisy input from a tuner source is shown in Figure 5. It demonstrates the difficulty in determining the synchronization information. Figure 6 illustrates the decoder output re-encoded into an analog format.

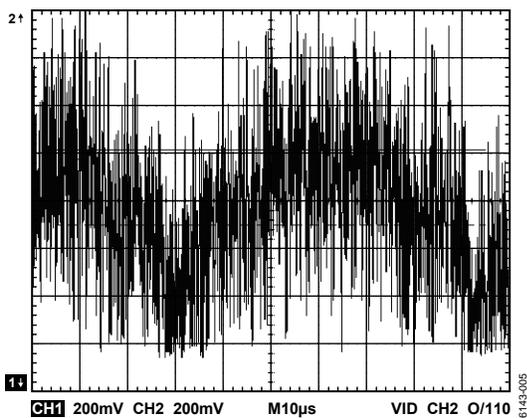


Figure 5. Actual Video Output from Tuner Source Measured on Input to Decoder

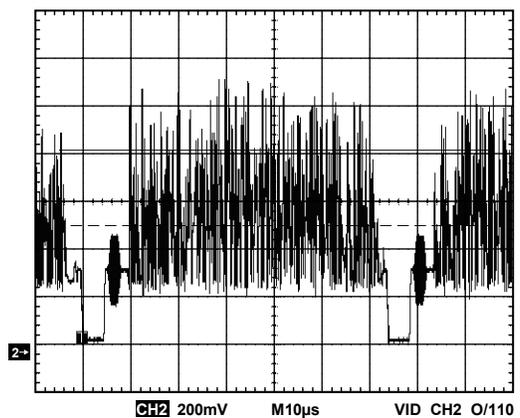


Figure 6. Decoder Output with Correct Noise-Free Synchronization Restored

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The introduction of noise is a common issue for video that has come through a transmission path. It is also common for components of the video signal to be attenuated or amplified, resulting in nonlinear characteristics in the video package. An example of a video signal seen at the input to the ADV decoder is shown in Figure 7. The synchronization level is reduced close to the blanking level, while the other components of the video signal remain at the proper amplitudes. The restored synchronization information, along with the other signal components that maintain their correct levels, is seen in Figure 8.

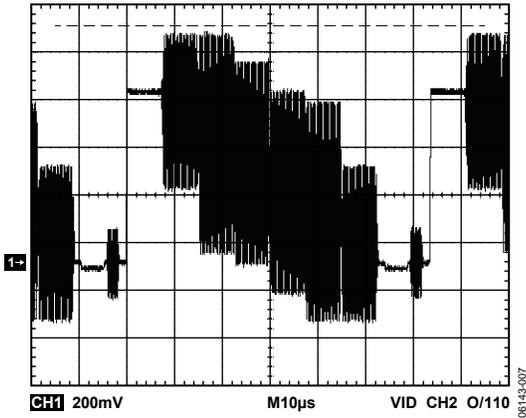


Figure 7. Input Video Signal with Attenuated Synchronization

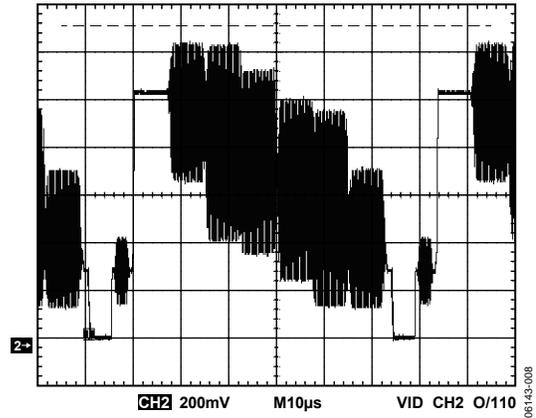


Figure 8. Output Video Signal with Correct Synchronization Level Restored

## VCR-INDUCED TIME-BASE ERRORS

Unlike common transmission path induced errors where synchronization is normally present but can be distorted, video from VCR sources can have missing or incorrect synchronization information. VCRs are essentially mechanical devices. Variance in mechanics such as motor speed, belt wear, and head switching can introduce time-base corruption. In the case of head switching and VCR trick modes, time base is not only corrupted, but can also be lost (see Figure 9). When head switching occurs, all video and synchronization is lost. The result is a flat dc output for this duration.

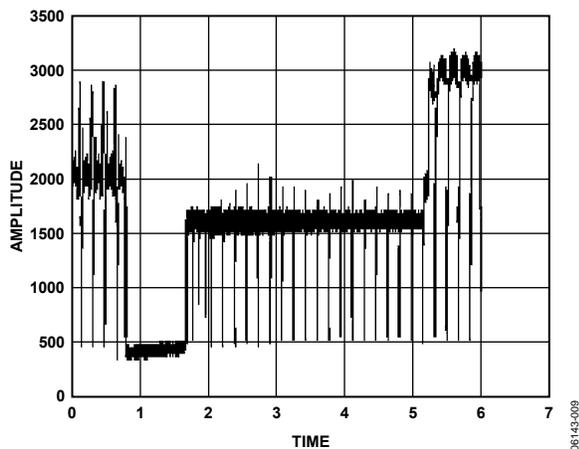


Figure 9. VCR Missing Signal During Head Switch

Such time-base errors normally result in lock in errors in the downstream HSYNC PLL and give rise to an artifact on the output image known as top curl (see Figure 10).

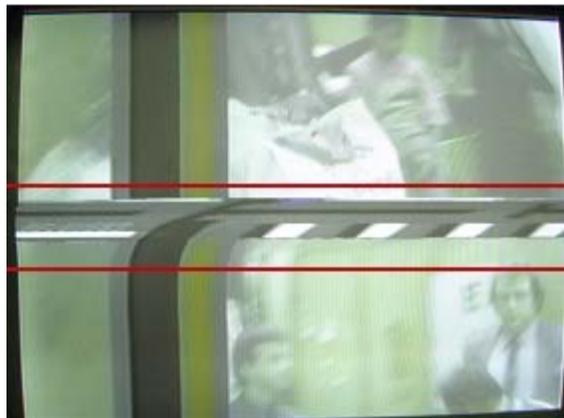


Figure 10. Output Image with Top Curl

The ADLLT technology of ADV decoders results in the correct restoration of the time base. The top curl, PLL lock in artifact is eliminated (see Figure 11).



Figure 11. Output Image with Top Curl Eliminated

## ADLLT

ADLLT incorporates the functionality of Analog Devices, Inc. (ADI) synchronous detection and extraction blocks, resampler, and advanced back end FIFO management.

ADI advanced digital video decoders filter the window in which they look to detect synchronization. In addition, the decoders use PLL blocks with HSYNC and VSYNC processor blocks to ensure that the synchronization information is correctly extracted. The filters ensure that the decoder gates the time in which it looks for synchronization information. Previously, excessive noise outside of this region would have dipped below the slice level and been seen as synchronization. This noise is now ignored. The synchronization PLL and processor blocks ensure that synchronization detected within the gated period is correctly aligned. Because line locked decoders use the HSYNC as a timing reference for color burst detection and subsequent video decoding, its proper detection is essential.

A critical requirement for any decoder is to correctly separate luma and chroma information. This is dependent on the decoder's ability to extract the color subcarrier and correctly generate the proper number of samples between each horizontal synchronization. ADI decoders use 54 MHz fixed frequency sampling to digitize the input video. The resampler block within

the decoder ensures that a fixed number of samples per line is consistently output. The resampler PLL varies in frequency to obtain this fixed number of samples. This resampling method that delivers a fixed number of samples between each horizontal synchronization is referred to as line locked time-base correction.

With this type of architecture, a simulated line lock clock (LLC) is generated. Note that although the line locked time-base correction results in a fixed number of samples per line, samples are not at a fixed 27 MHz rate, but vary with the resampler PLL, that is,  $27 \text{ MHz} \pm 5\%$ .

Pixel information is fed to the output FIFO before it is output from the decoder. Advanced FIFO control techniques are used to allow for a smooth flow of data from the FIFO to the output pixel drivers. Although the long-term clock jitter is still present on the output clock, the short-term jitter variations are smoothed out. Figure 12 provides a representation of output jitter across two fields of video. The peak jitter measurement is the same on both plots, but the short-term jitter in the left plot has been removed. This ability to remove short-term jitter allows the decoder to now operate in a direct back-to-back configuration with the digital video encoder.

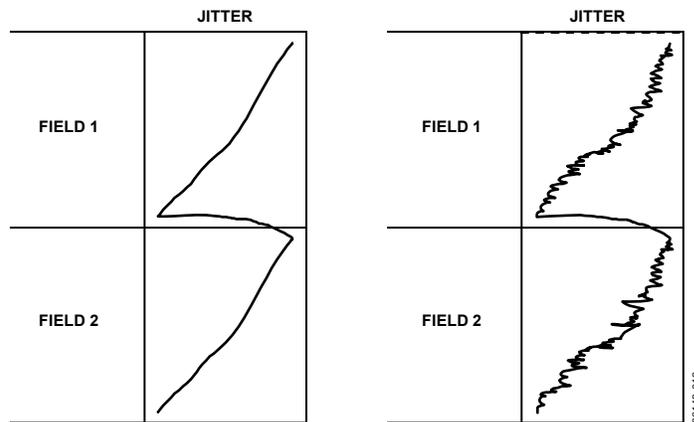


Figure 12. LLC Jitter Performance

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